



# AFRY X Real Digital Twin

ACCELERATE YOUR BUSINESS BY SIMULATING ITS NEXT STEPS

# Digital Twin solutions cover a wide range of capabilities

RDT's strength in emulation drives higher precision and quality in all other areas

## Visualization

- Advanced visualizations for human centric insights

## Simulation

- Provides an approximation of the behaviour of end to end systems or processes

## Emulation

- An exact digital replica of the production system behaves and generates data identically to the physical twin

## Optimization

- Improve business resiliency through more accurate forecasting and modelling of operational issues and their impact on performance

# Why a smarter factory?

## Targets:

- Increase productivity
- Reduce costs
- Assure quality
- Minimize risks

The industry's ability to implement and use new digital technologies will be crucial in today's competitive environment

Adapting digital technology and transforming it into productivity increase and cost reduction

AFRY's own iterative processes, using digital tools, have shown productivity improvements and cost reductions of up to 80%

# The roadmap towards a smarter factory

Most companies have too many digitalization initiatives that are not connected – what's the purpose?

Develop a vision to use virtual technologies based on real facilities, real data and real systems

The right tool for maximum value – different parts of the plant have different needs

Be more competitive by:

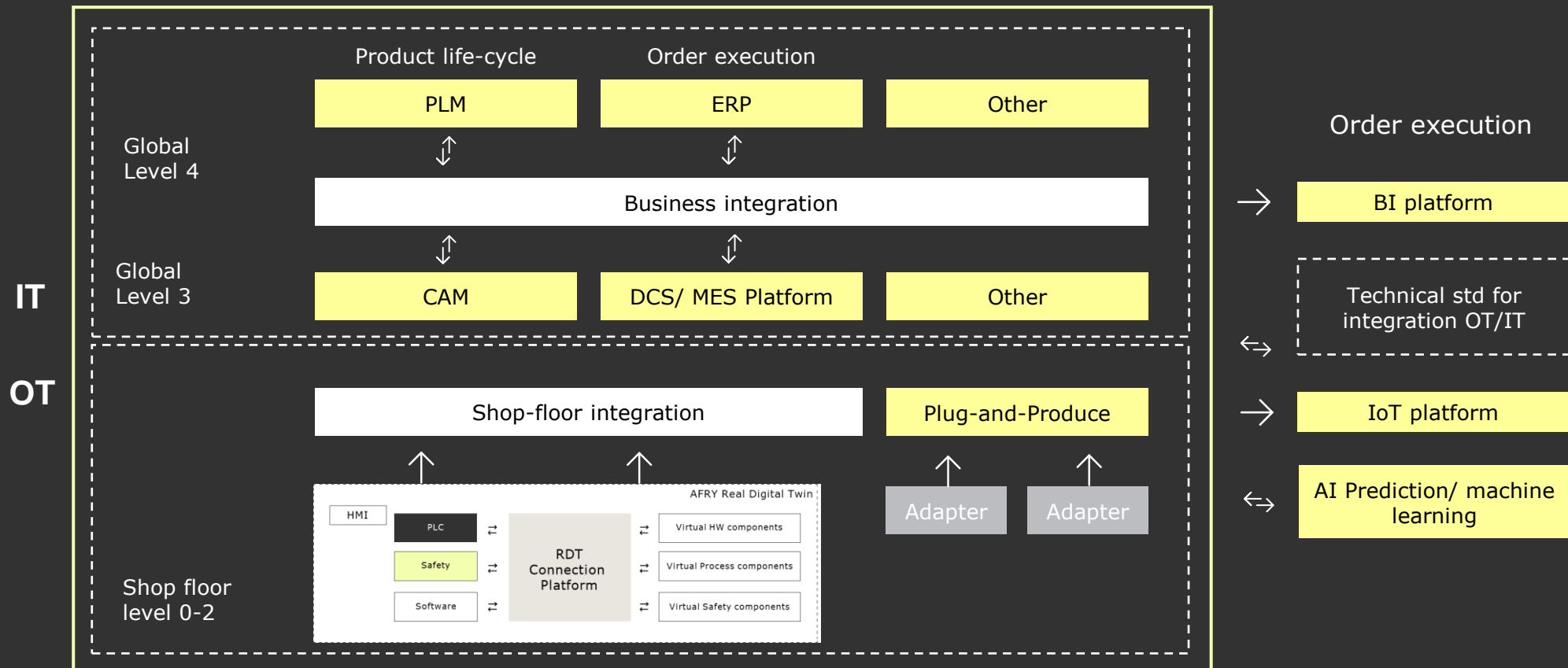
- Develop processes and working methods that support continuous improvement
- Increase your competence in digitalization
- Introduce the right digital tools that create measurable value and simplify everyday life
- Dismantle unnecessary systems, streamline your data flows

Find the best way forward in the digitalization journey

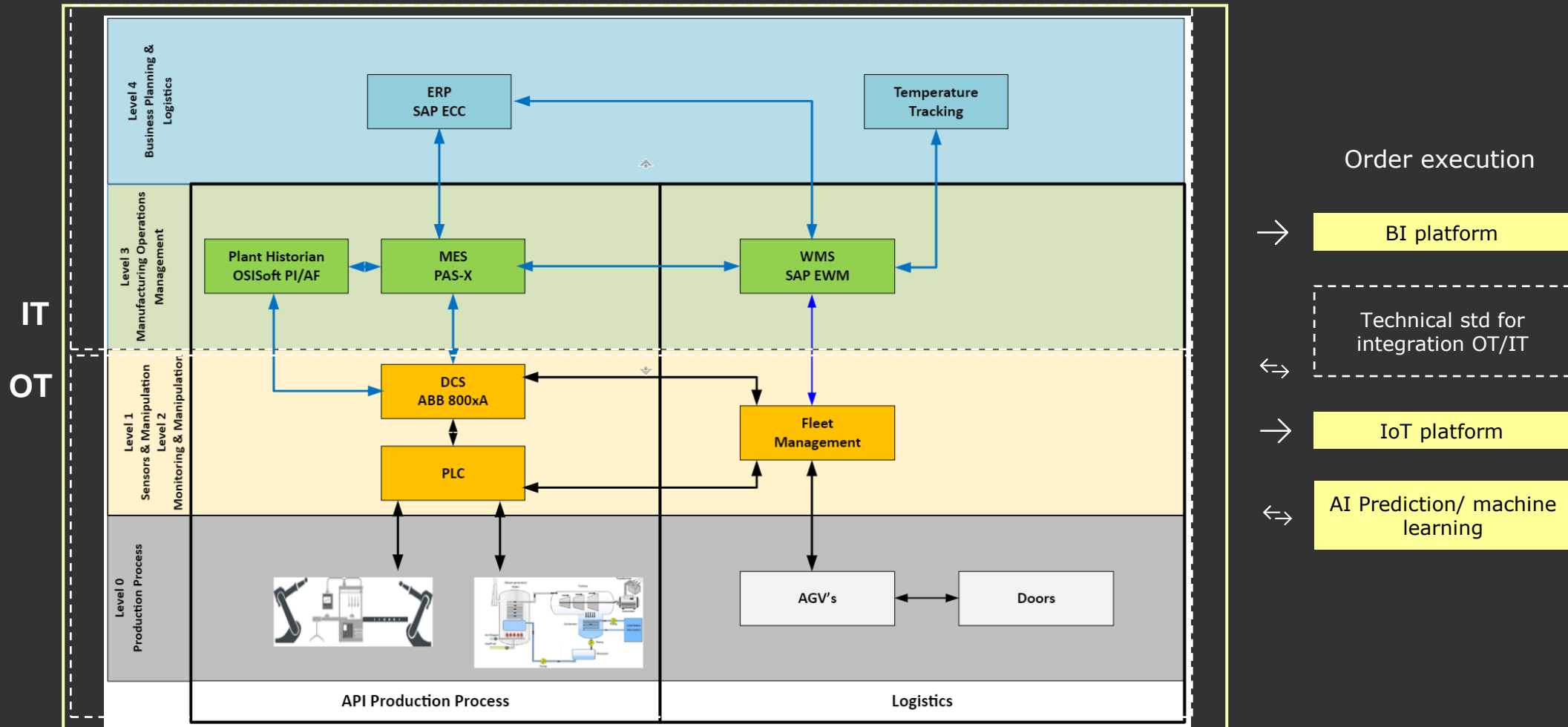
Connect your production, collect real data and be able to take fact-based decisions

# The digital thread

## - addressing the smart factory



# The digital thread - Example



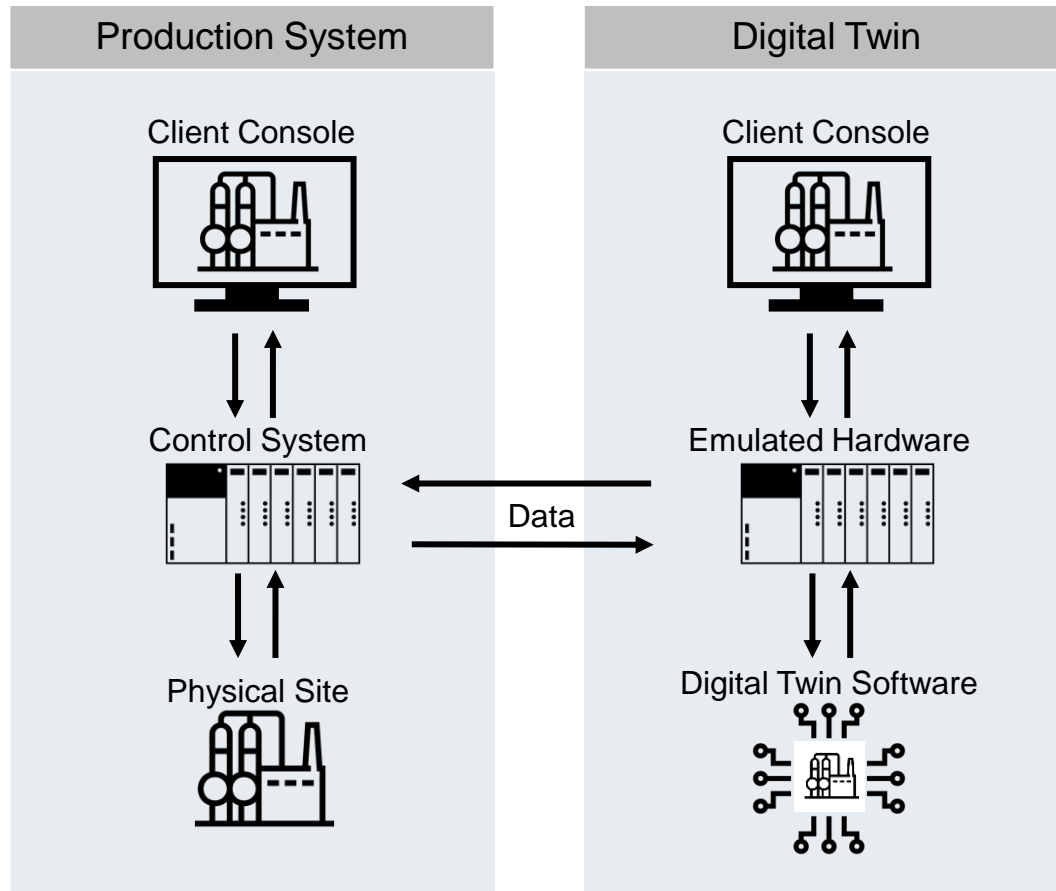
# AFRY X Real Digital Twin

ACCELERATE YOUR BUSINESS BY  
USING AFRY REAL DIGITAL TWIN

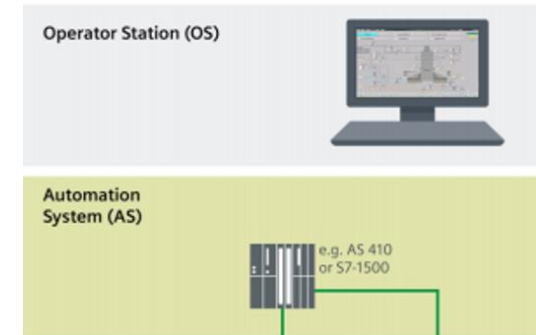
- TEST BED FOR AUTOMATION
  - Increased quality
- VIRTUAL COMMISSIONING
  - Reduced downtime and shorter ramp-up time
- OPERATOR TRAINING
  - Skill training
- LIFE CYCLE VALUE – OPTIMIZATION (AI ETC.)
  - Efficiency and cost reductions over time



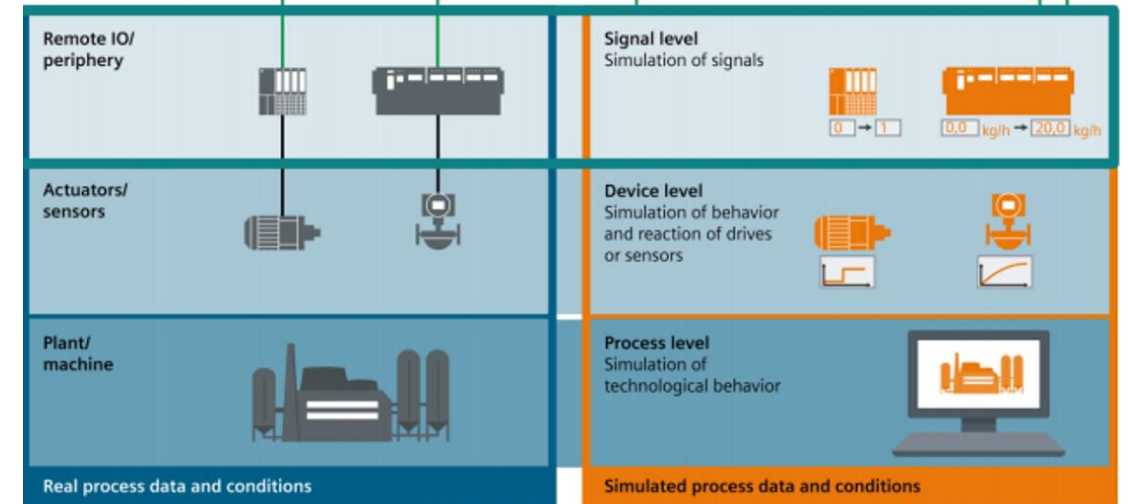
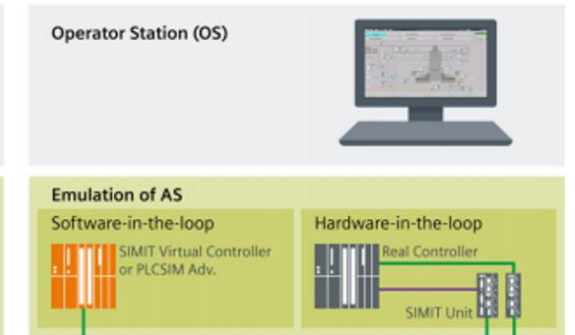
# The Process Digital Twin



## Real plant environment



## Virtual plant environment





# AFRY X Real Digital Twin

# Component emulation rather than simulation

## SIMULATION

Optimization from **GIVEN** behavior

- + Simplified system test bed
- + Flexible setup
- + Relatively easy

*A simulator copies something from the real world into a virtual environment – often to give you an idea about how something works. It simulates the basic behavior but doesn't necessarily abide to all the rules of the real environment that it simulates.*

## EMULATION

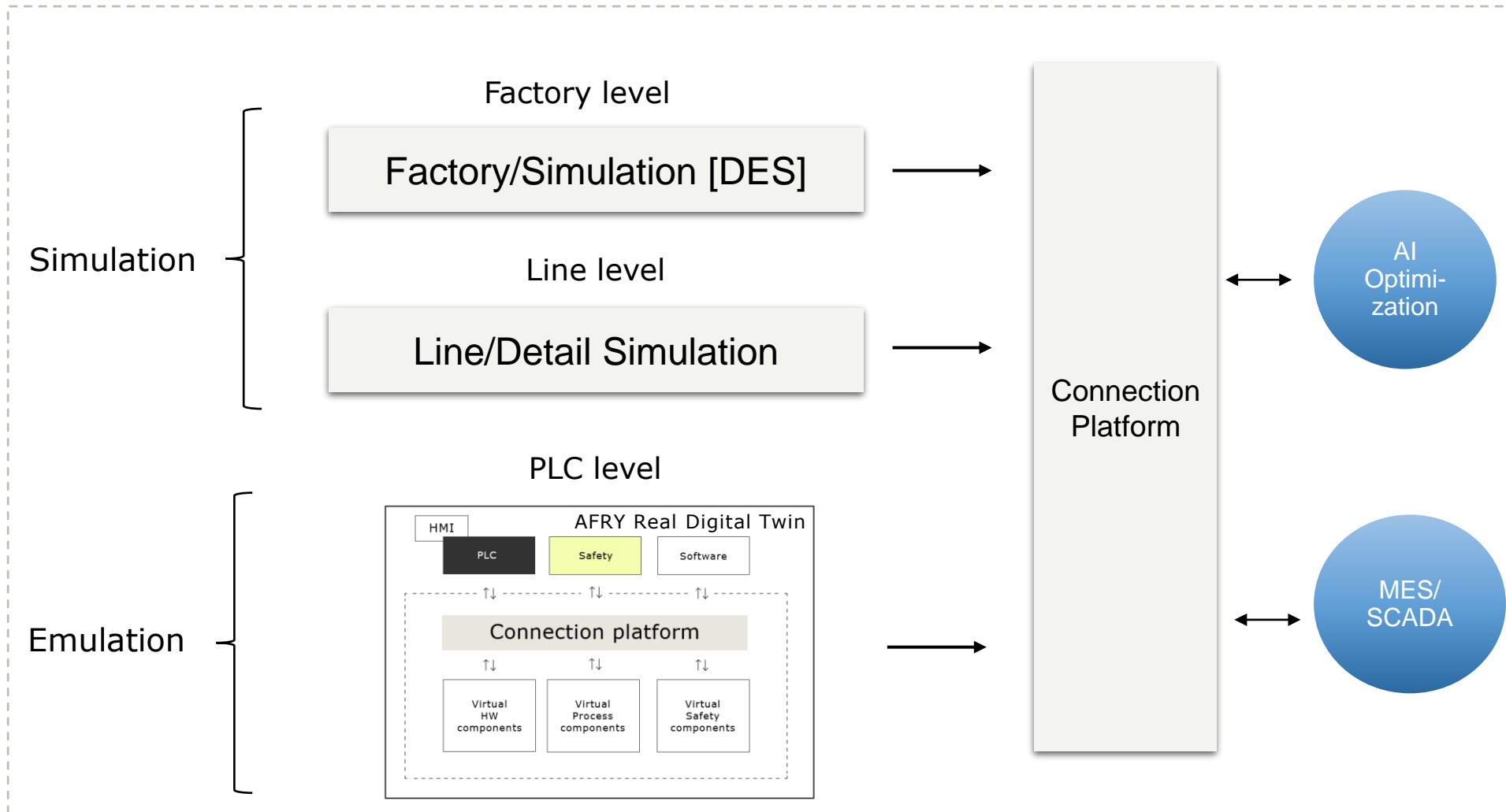
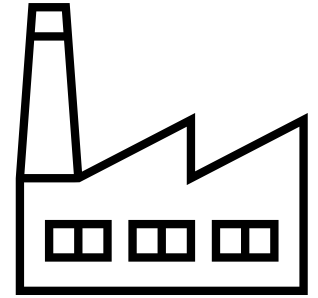
Optimization from **ANY** behavior

- + Advanced system test bed
- + Actual setup
- + Real time interfaces

*An emulator, on the other hand, duplicates the equipment as they are. The emulation is efficiently a complete imitation of component behavior – it just operates in a virtual environment instead of the real world. Control system communication 1:1 (virtual:reality)*

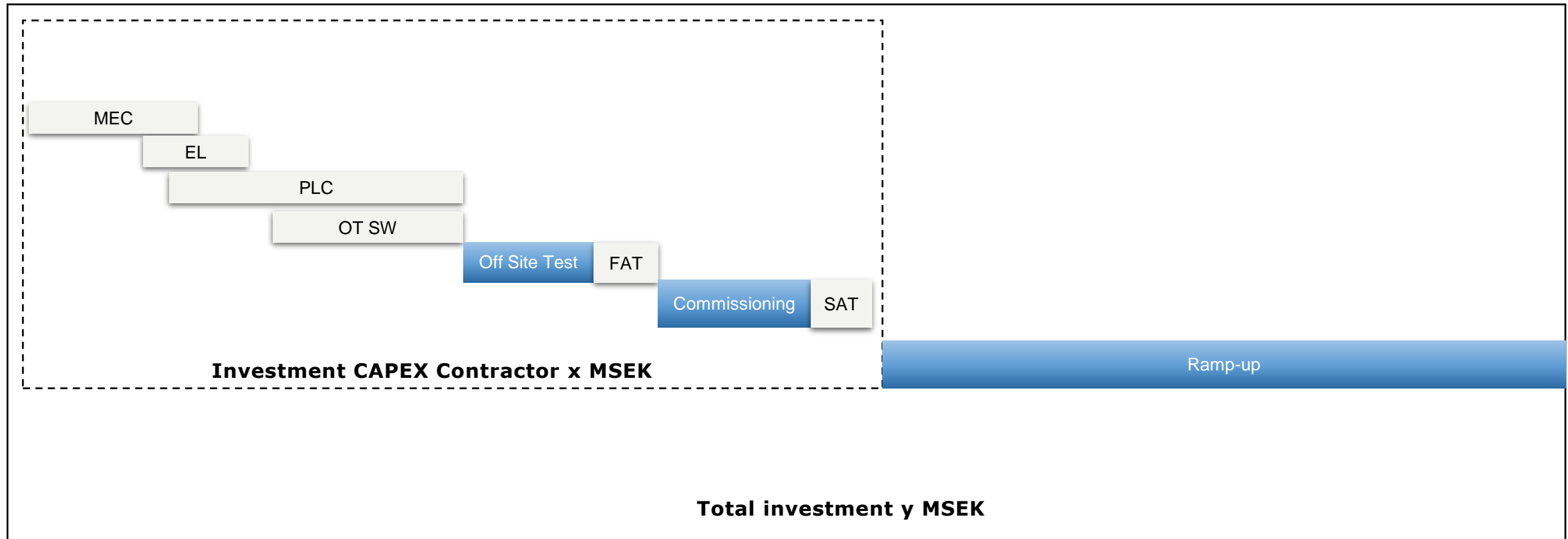


# Connect Simulation & Emulation

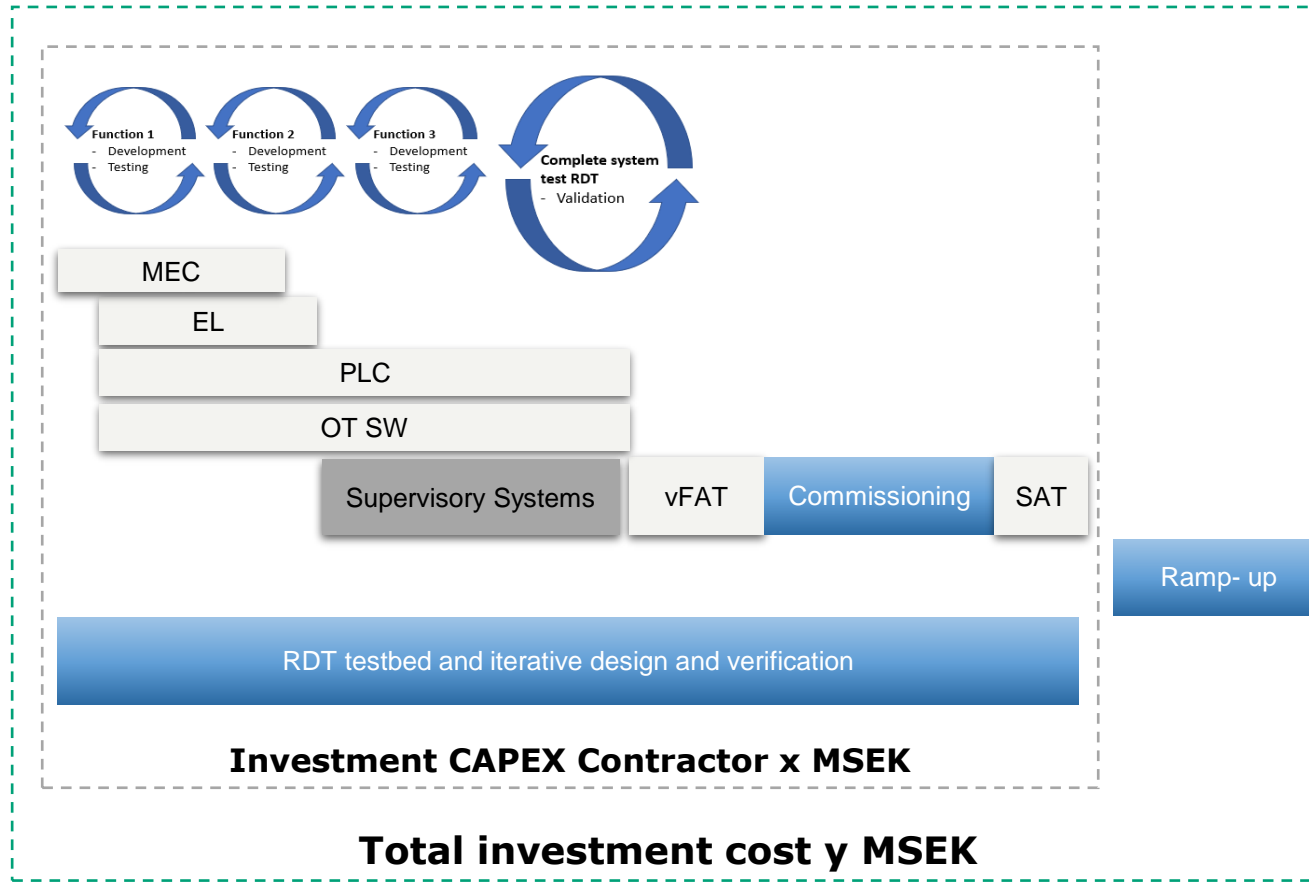


# Todays - project way of working

v1 v2 v3 v4 v5 v6 v7 v8 v9 v10 v11 v12 v13 v14 v15 v16 v17 v18 v19 v20 v21 v22 v23 v24 v25 v26 v27 v28 v29 v30 v31 v32 v33 v34 v35 v36 v37 v38 v39 v40



# New agile RDT way of working

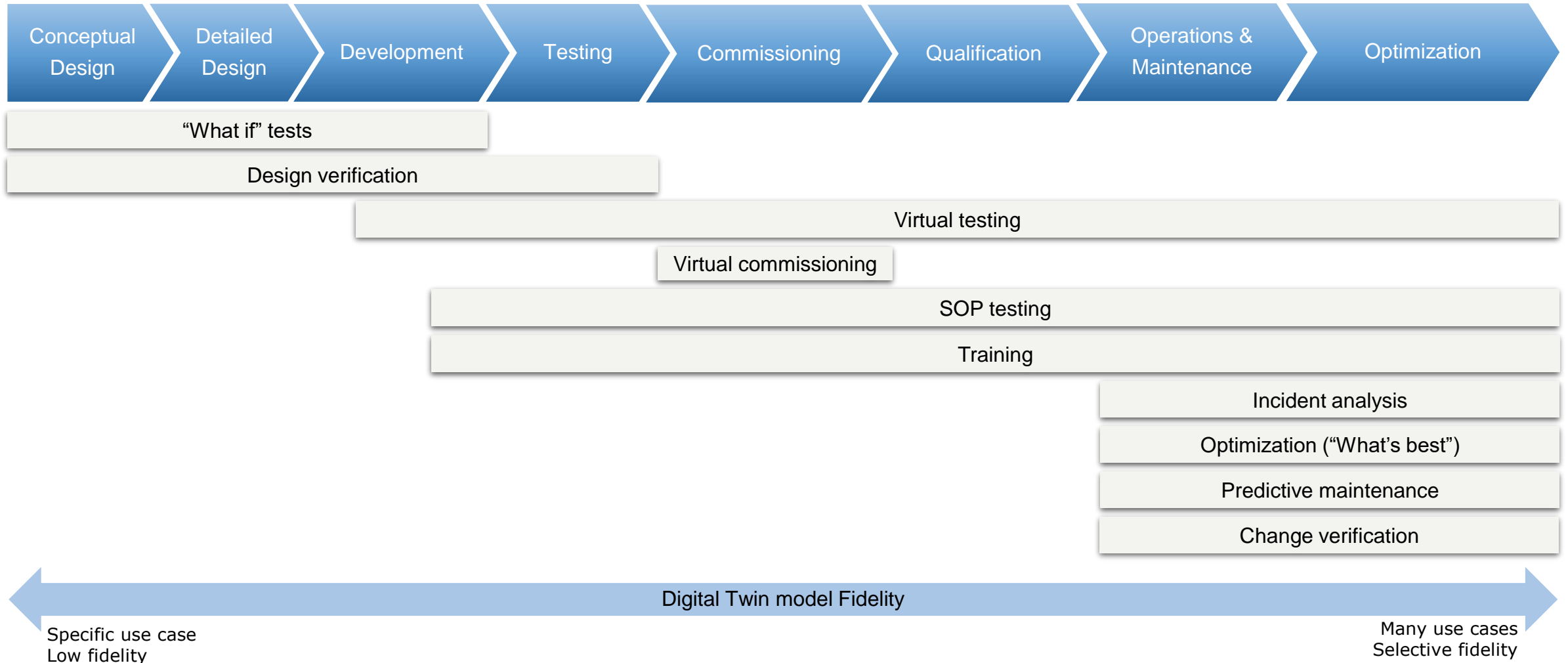


## Result

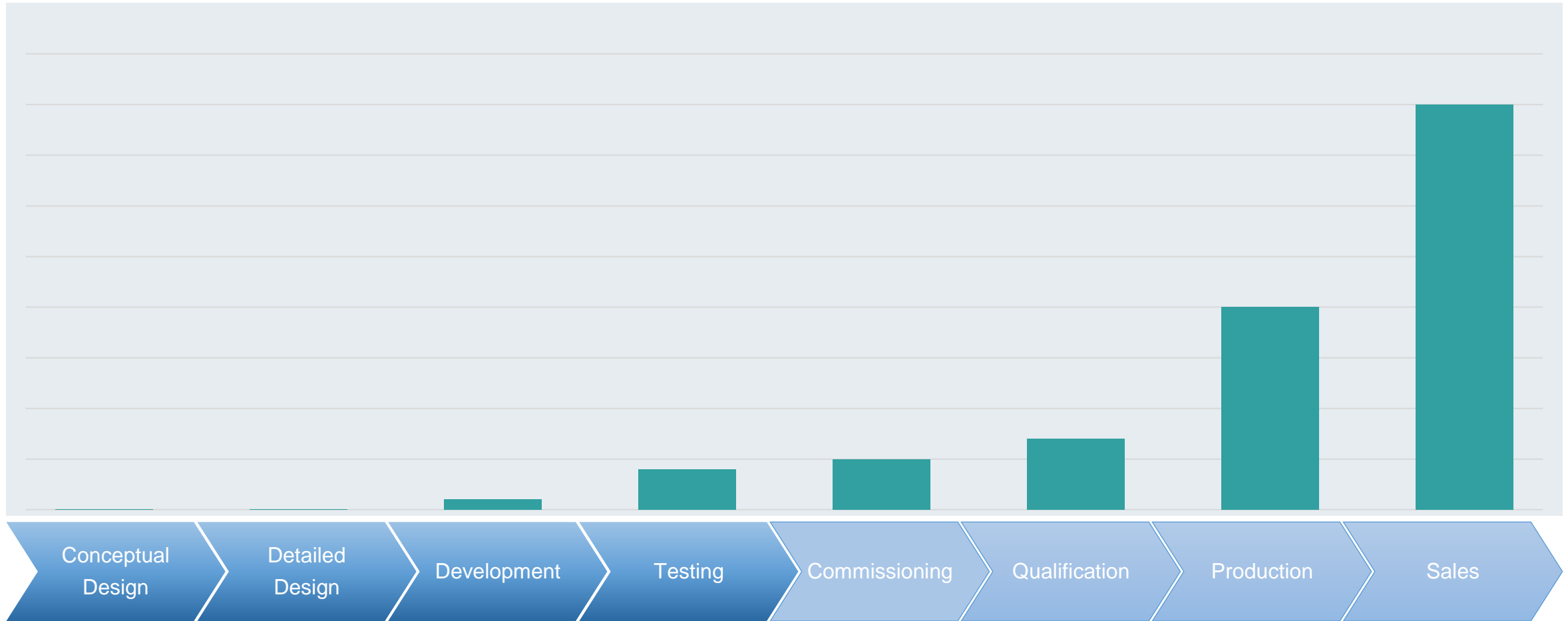
- Reduced total cost
- Better quality
- Digital Twin

**-xx M\$ek**

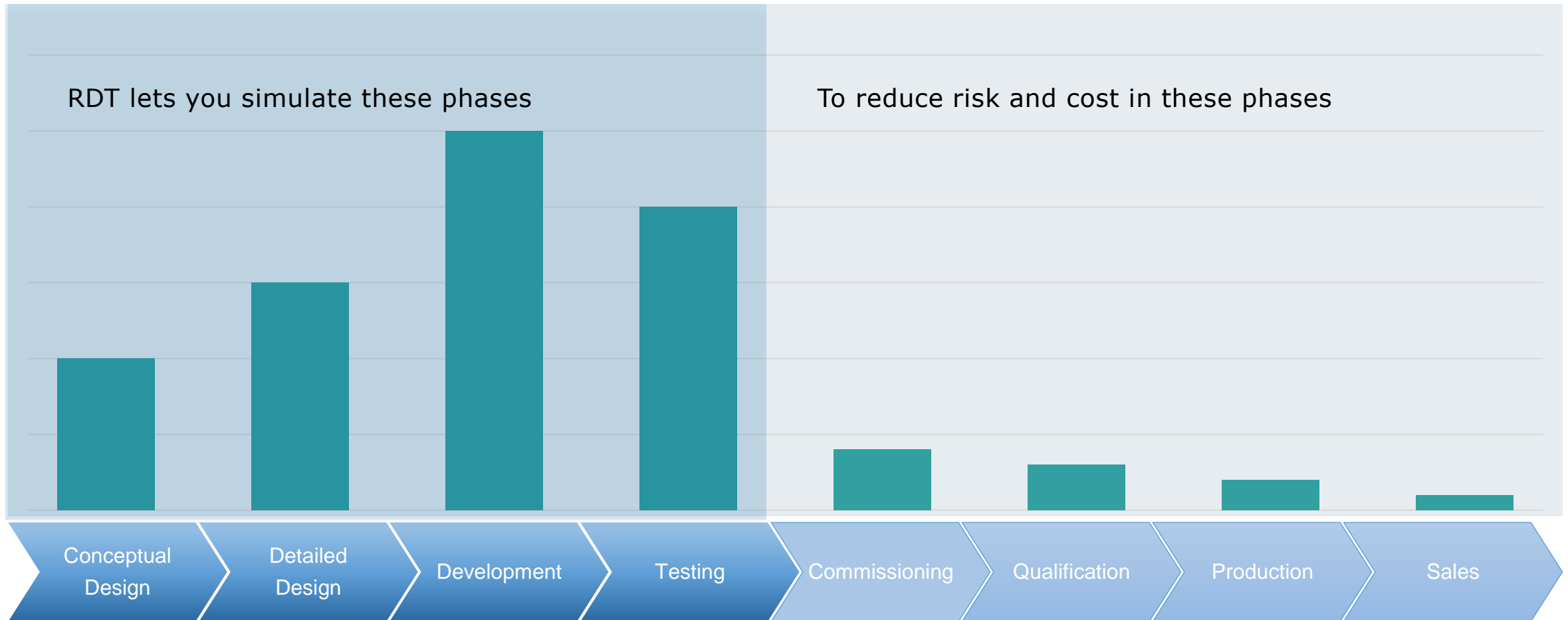
# Real Digital Twin in the Life Cycle



# Cost of Design Changes/ Faults

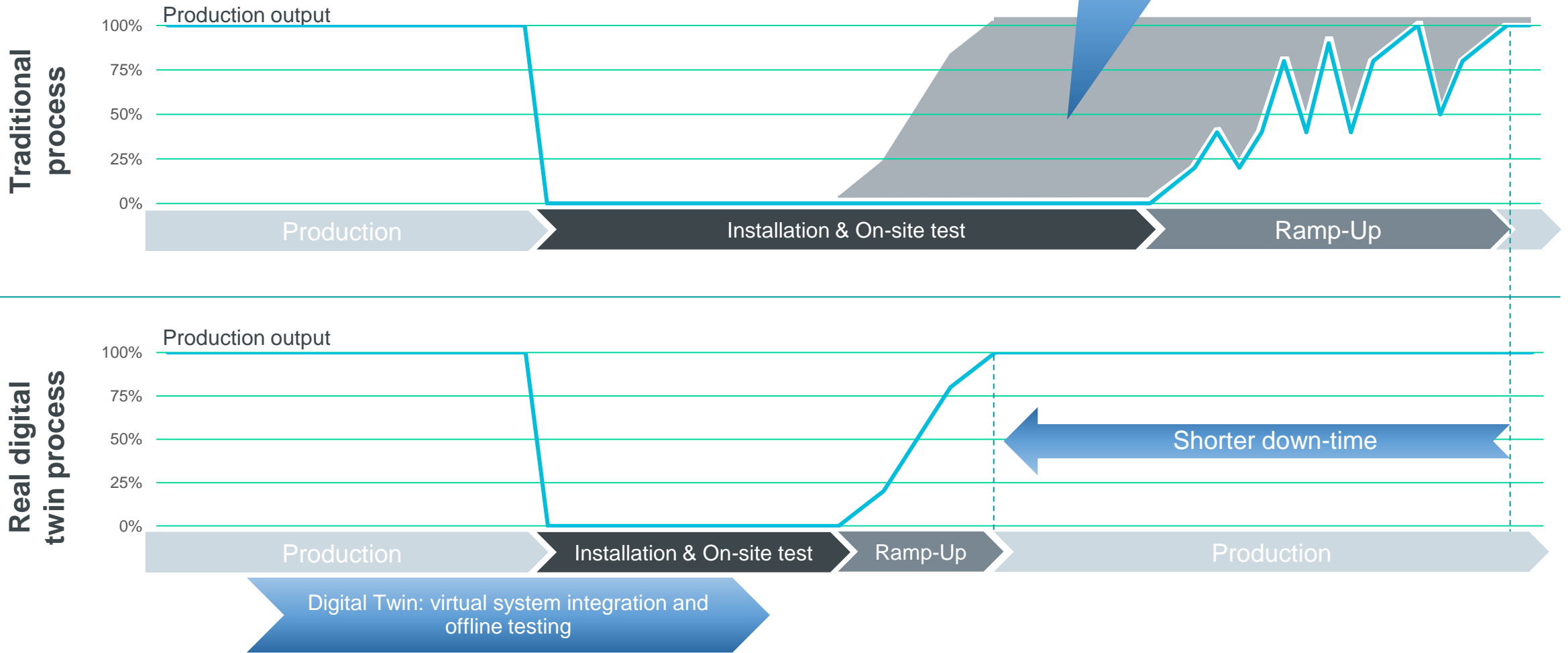


# Fix issues earlier - Fail early - Massive cost reduction





# Implementation Value RDT



# The Business Case

## Reduced time & cost

- Replace own simplified self-tests with accurate RDT test-bed (sandbox)
- Reduce commissioning and ramp-up time up to 80%
- Reduce overall project development time due to accurate OT test-bed

## Minimize risk

- Iterative testing of developed OT systems gives higher code quality
- Unlimited virtual stress tests to improve quality
- Realistic operator training in real OT/IT systems

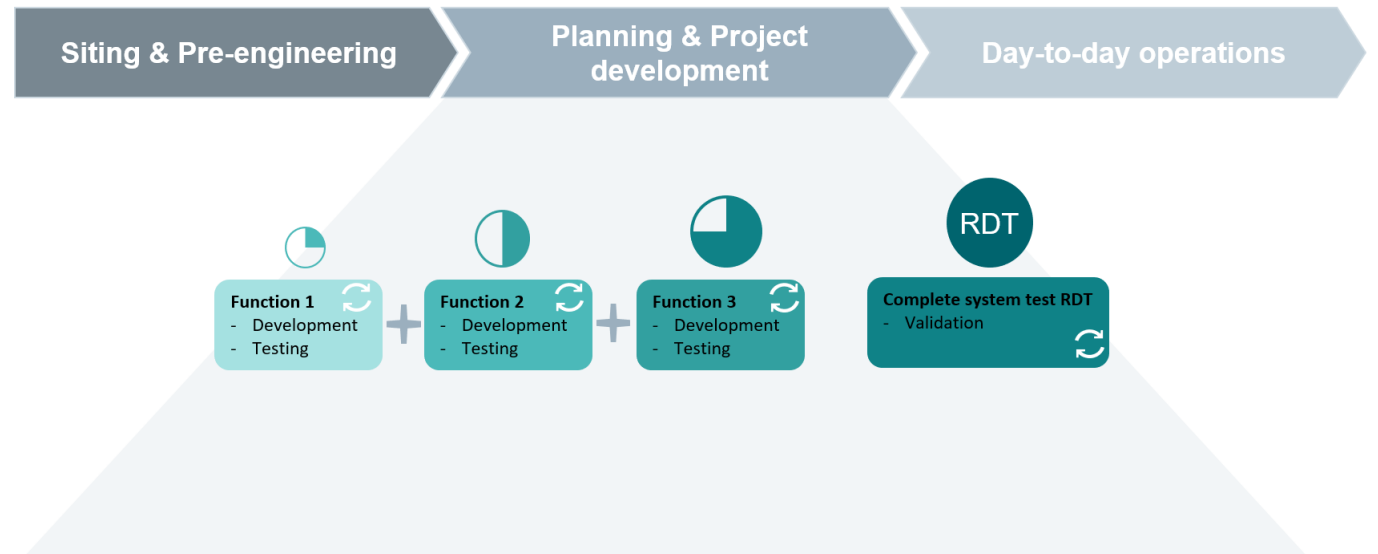
## Increase success rate of qualifications

- Use to verify and improve PLC code, find and correct issues that otherwise would not be found before commissioning phase
- Accurate emulated test bed for OT/IT integration (SCADA, MES, IT)
- Commission a control system with higher quality, further stress tested and a faster ramp-up time

## Life cycle perspective

- Share knowledge regarding agile WoW and tools to further develop your digitalization
- Test bed for supervisory systems (OSI PI etc.) and AI integration, generating industrial IoT data
- Patching, training, trouble shooting and optimization

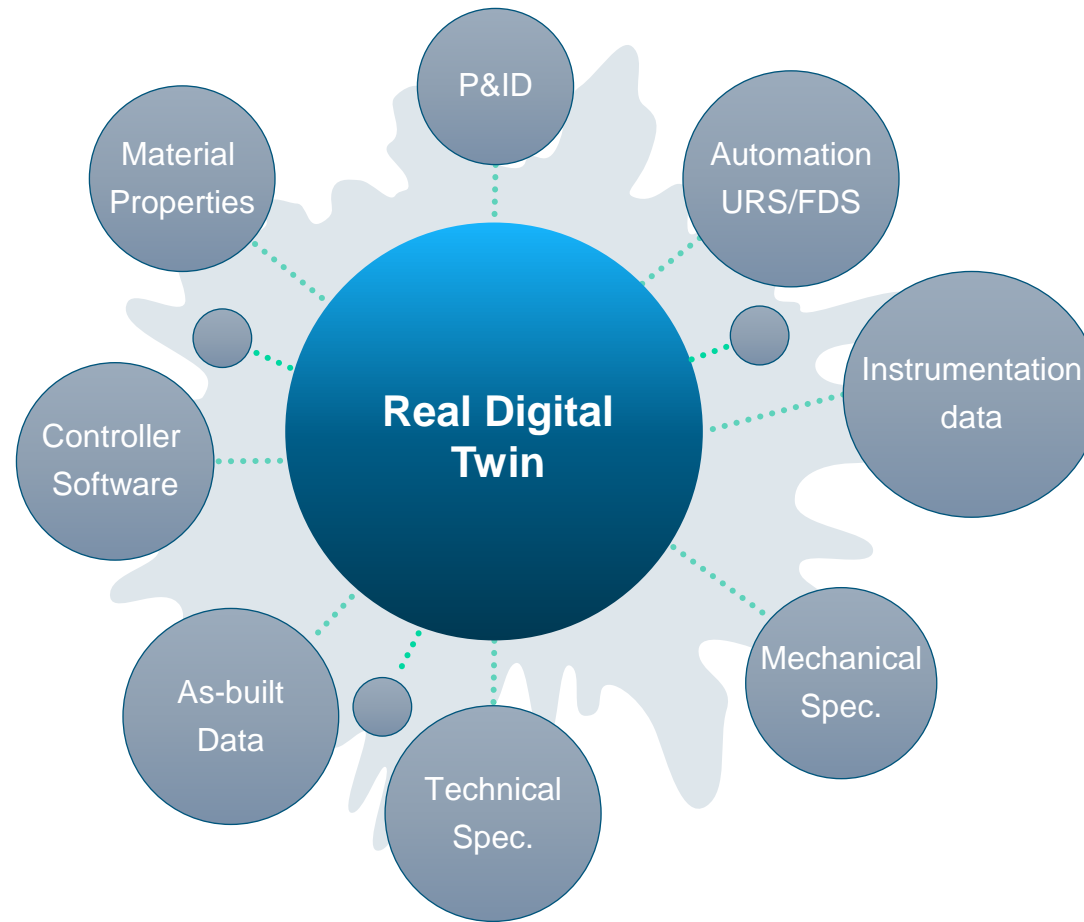
## Real Digital Twin – Applicable over complete Asset Lifecycle



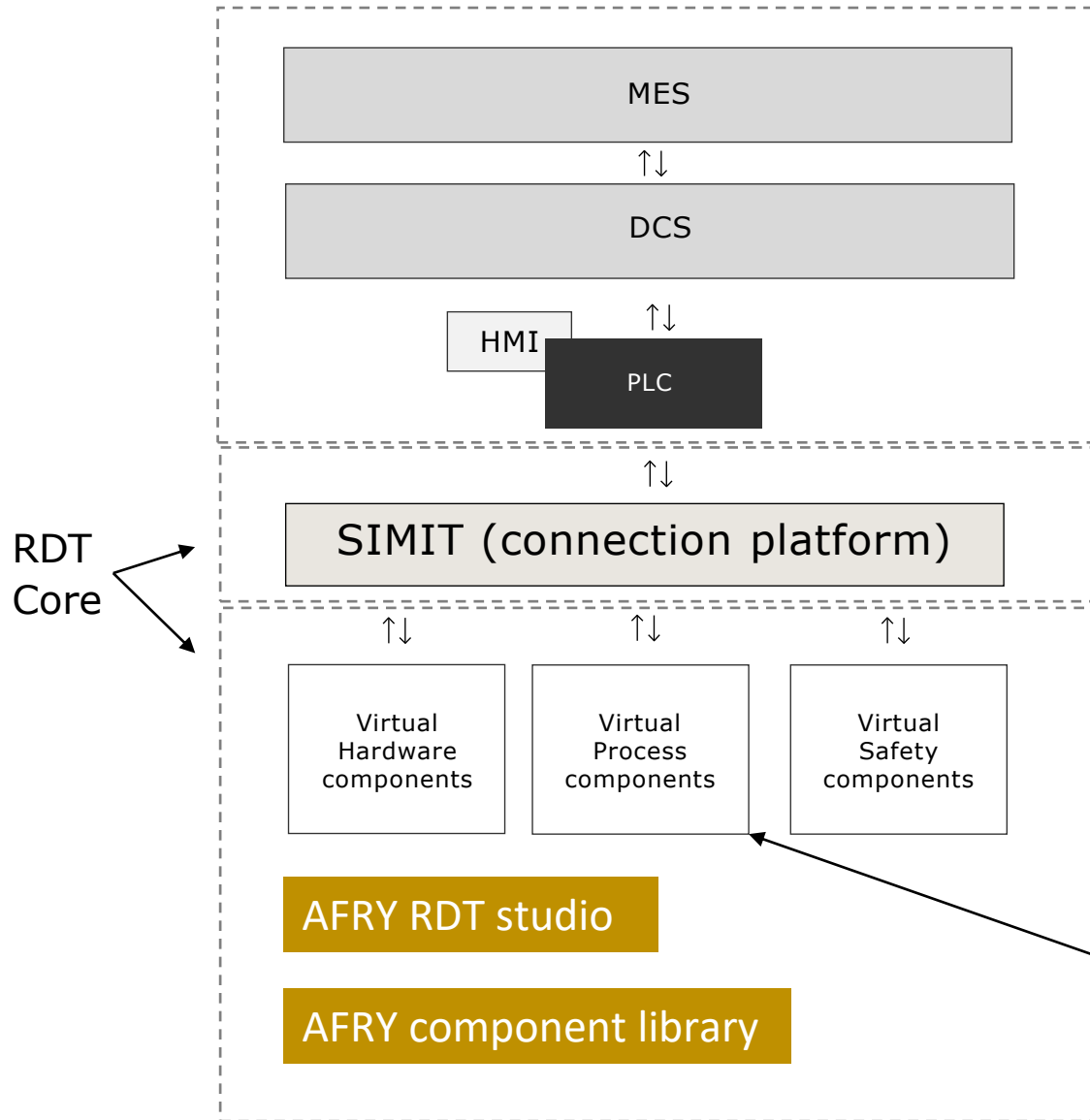
AFRY X REAL DIGITAL TWIN

# How it works

# Building the Digital Model



# The architecture

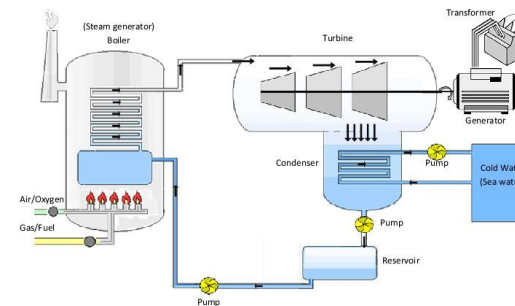


## AFRY RDT Studio

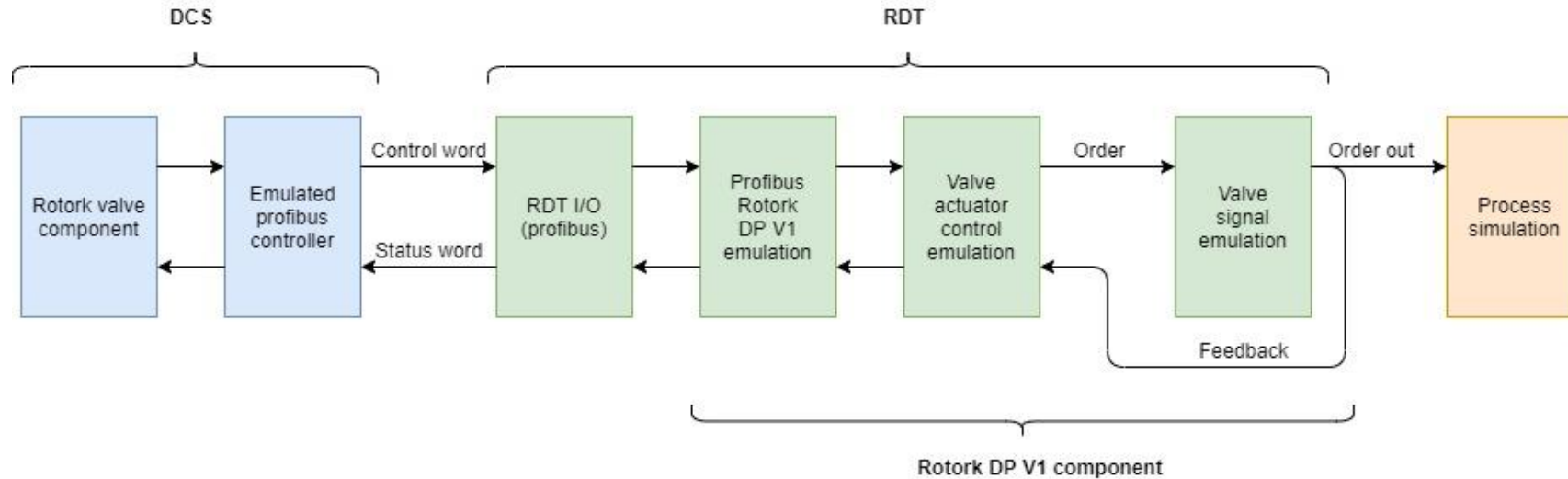
- Software products for data washing
- Faceplates & templates
- Tools for generating couplings & signal interface
- Tools for generating the testbed

## AFRY RDT Component Library

- AFRY component library
- Behavior models, process step relations



# Connecting DCS, RDT and advanced process Simulation



Connecting RDT emulation to advanced process simulation tools creates extensive value and enables new possibilities.

Re-use, Re-connect, Re-scale between different DCS/SCADA systems and process simulations

HOW IT WORKS

# AFRY's virtual Hardware library

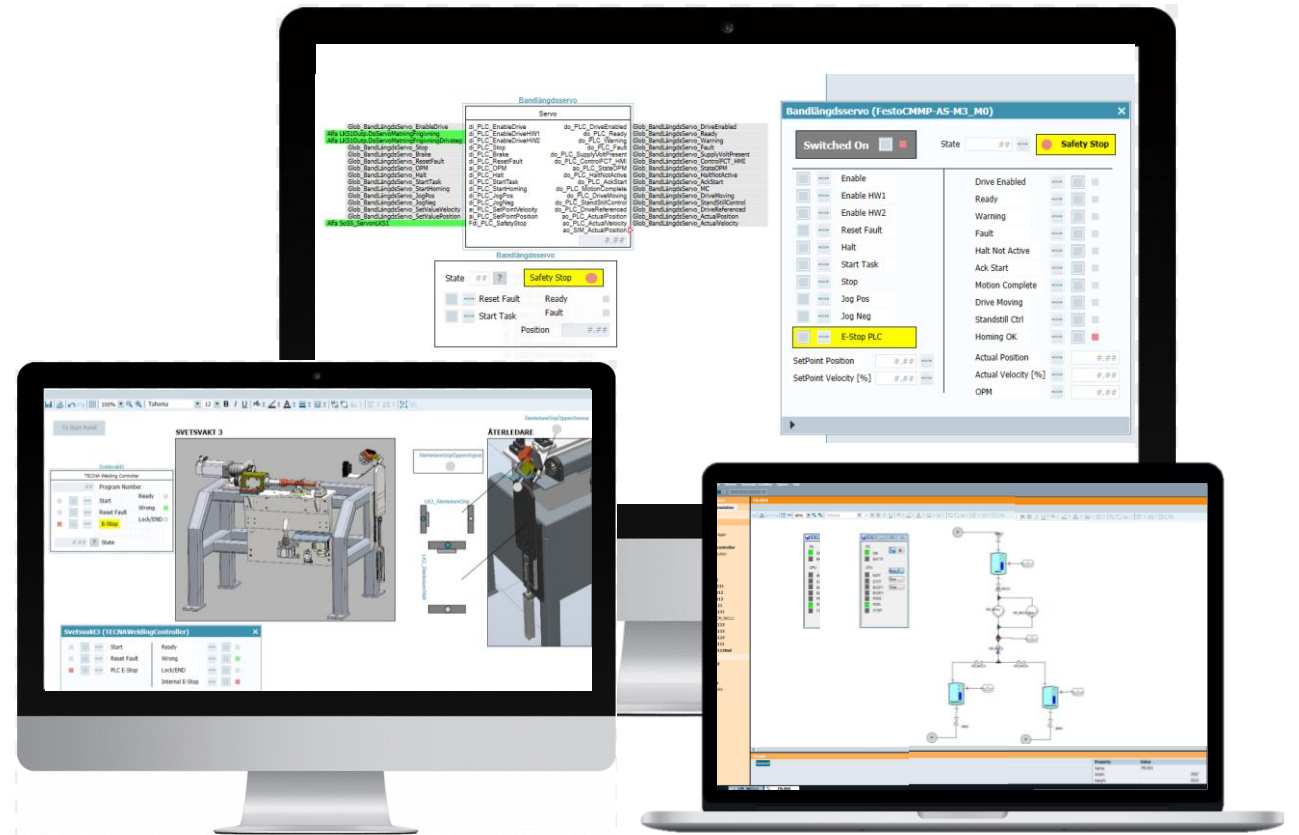
AFRY has developed a library of hundreds of virtual hardware and process components allowing clients to quickly emulate their physical systems in RDT.

Each virtual component has their I/O connected to the corresponding tag and simulates the signal behavior of the real components.

New components are created as needed and added to the library continually, based on the FMU / FMI standards

**FMU** – Functional Mockup unit

**FMI** – Functional Mockup Interface



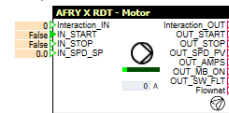
## HOW IT WORKS

# Structured modular components

## AFRY\_Motor\_Binary

### Screenshots

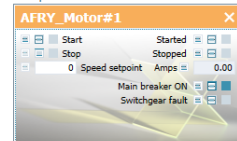
Component:



Link:



Faceplate:



### Description

Requirements: SIMIT 10.1

Component for emulating motors, such as pumps, fans etc. Different input configurations is possible which is described below. The component is intended to be used with flownet controlling flownet pumps, fans, compressors etc. The link for the component is also designed for that purpose. Switchgear fault and mainbreaker on are also possible as outputs. Both standard ON/OFF-pumps and pumps controlled by setpoint is possible.

### Supplier documentation

PDF documentations:

[Manual for motor drive ACS880 from ABB](#)

[Manual for RPBA profibus protocol for ACS-drives from ABB](#)

### Version

1.0

New component.

### Configuration

#### Parameter

##### AUTO

Default TRUE

If not true, the component isn't running.

##### MaxRampTime\_ms

Default 3000

Sets the ramp time from 0-100% RPM and vice versa.

##### Label

The text that will be shown on the component and link tooltip, most often the name/id of the valve.

##### max\_amps

Default 40.0

Maximum current on motor.

##### Motor\_configuration

###### - ON and OFF (pulsed/hold) default

If IN\_START pulses TRUE the motor starts to 100%.

If IN\_STOP pulses TRUE the motor stops to 0%.

###### - ON only (false = OFF)

If IN\_START is TRUE the motor starts to 100%.

If IN\_START is FALSE the motor stops to 0%.

###### - ON and OFF with setpoint

If IN\_START pulses TRUE the motor starts to selected setpoint on input (IN\_SPD\_SP).

If IN\_STOP pulses TRUE the motor stops to 0%.

###### - ON only with setpoint

If IN\_START is TRUE the motor starts to selected setpoint on input (IN\_SPD\_SP).

If IN\_START is FALSE the motor stops to 0%.

##### Motor\_type

###### - Motor default

Shows motor icon.

###### - Fan

Shows fan icon.

###### - Pump

Shows pump icon.

###### - Compressor

Shows compressor icon.

##### MB\_ON\_Default

Default TRUE

Mainbreaker ON start value.

##### SW\_FLT\_Default

Default FALSE

Switchgear fault start value.

### Signals

Name	Type	Comment
Interaction_IN	Integer input	Interaction IN (see table below)
Interaction_OUT	Integer output	Interaction OUT (see table below)
IN_START	Binary input	Command start
IN_STOP	Binary input	Command stop (if used)
IN_SPD_SP	Analog input	Setpoint (if used)
OUT_START_CLS	Binary output	Indicated start
OUT_STOP_CLS	Binary output	Indicated stop
OUT_SPD_PV	Analog output	Indicated PV (RPM%)
OUT_AMPS	Analog output	Indicated current
OUT_MB_ON	Binary output	Indicated mainbreaker on
OUT_SW_FLT	Binary output	Indicated switchgear fault
Flownet	Analog output	Connect to object in flownet (0-100%)

### Interaction parameters IN

Bit	Comment
0	Start motor, same as signal on IN_START (can collide if not used carefully)
1	Stop motor, same as signal on IN_STOP (can collide if not used carefully)
2	Mainbreaker ON, can be used to switch state on OUT_MB_ON
4	Switchgear FAULT, can be used to switch state on OUT_SW_FLT

### Interaction parameters OUT

Bit	Comment
0	Motor ON
1	Motor OFF
2	Mainbreaker ON
3	Switchgear FAULT



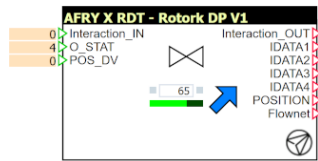
HOW IT WORKS

# Structured modular components

## AFRY\_ROTORK\_DP\_V1

### Screenshots

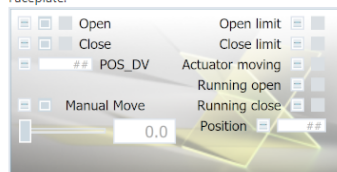
Component:



Link:



Faceplate:



### Description

Requirements: SIMIT 10.2

Component for emulating ROTORK-valve with Profibus DP-V1 acyclic messages. Different input configurations is possible which is described below. The component is intended to be used with in flownet simulation interacting with media flow. The link for the component is designed to give a visual feedback for certain operating state. The component issues actuator commands to open, stop, close, preform and EDS operation or move to a set position. It is also possible to manually move the valve after setting "Manual Move" to TRUE.

### Version

1.0

New component.

### Configuration

#### Parameter

##### AUTO

Default TRUE

If not true, the component isn't running.

##### MaxMovingTime\_ms

Default 10000

Sets the maximum time for a complete sequence from completely closed (0%) to fully open (100%) and vice versa.

##### Label

The text that will be shown on the component and link tooltip, most often the name/id of the valve.

### Signals

Name	Type	Comment
Interaction_IN	Integer input	Interaction IN (see table below)
Interaction_OUT	Integer output	Interaction OUT (see table below)
O_STAT	Integer input	Register containing control commands (see table below)
ACTCON	Internal Register	Register interpreting control commands (see table below)
POS_DV	Integer input	Desired position value to move should be placed in the POS_DV Register (see table below)
IDATA1	Integer output	Dataset relating the status of the actuator (see table below)
IDATA2	Integer output	Dataset relating the status of the valve (see table below)
IDATA3	Integer output	Dataset relating the status of the card connections (Not implemented)
IDATA4	Integer output	Dataset relating the status of the card conditions (Not implemented)
POSITION	Analog output	Current position of the valve (0-1000)
Flownet	Analog output	Connect to object in flownet (0-100%)

#### Interaction parameters IN

Bit	Comment

#### Interaction parameters OUT

Bit	Comment

#### POS\_DV Register

Name	Value range
Register value	0 to 1000 (0 to 3EB)
Position demand	0.0% to 100.0% of valve travel

#### O\_STAT Register

O_STAT Register				
Bit 4-15	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	DO-4	DO-3	DO-2	DO-1

#### ACTCON Register (Internal interpretation of O\_STAT Register?)

ACTCON Register						
Bit 6-15	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	Partial Stroke	Position Enable	ESD	Open	Close	Stop

# References

## Some client storys



*“By using the advanced twin technology, we can accelerate our work towards a more digital and automated production which is well in line with our Industry 4.0 strategy,” says Mikael Tydén, President of the Operations Division.*



*“Turn-key projects within AFRY uses AFRY X RDT as a key enabler for successful implementation and quality insurance,” says Michael Mjörnestål, Head of Advanced Manufacturing*



*“Through this solution, we are strengthening our competitiveness in the global market, while once again demonstrating our commitment to a safe and ergonomic working environment. Like our technology, our production must be at the forefront of what is possible to meet the increased demand for products and solutions that will enable the green energy transition,” said Andreas Berthou, Global Product Group Manager of Hitachi ABB Power Grids’ HVDC & HVDC Service business.*

## Some client KPI's



Reduction of commissioning/ramp up time with 50%.



Reduction of commissioning/ramp up time with 80%.



Reduction of commissioning/ramp up time with 80%.

# Making Future