

# SIMATIC S7-PLCSIM Advanced V2.0

Overview over the highlights of the V2.0 and V2.0 SP1

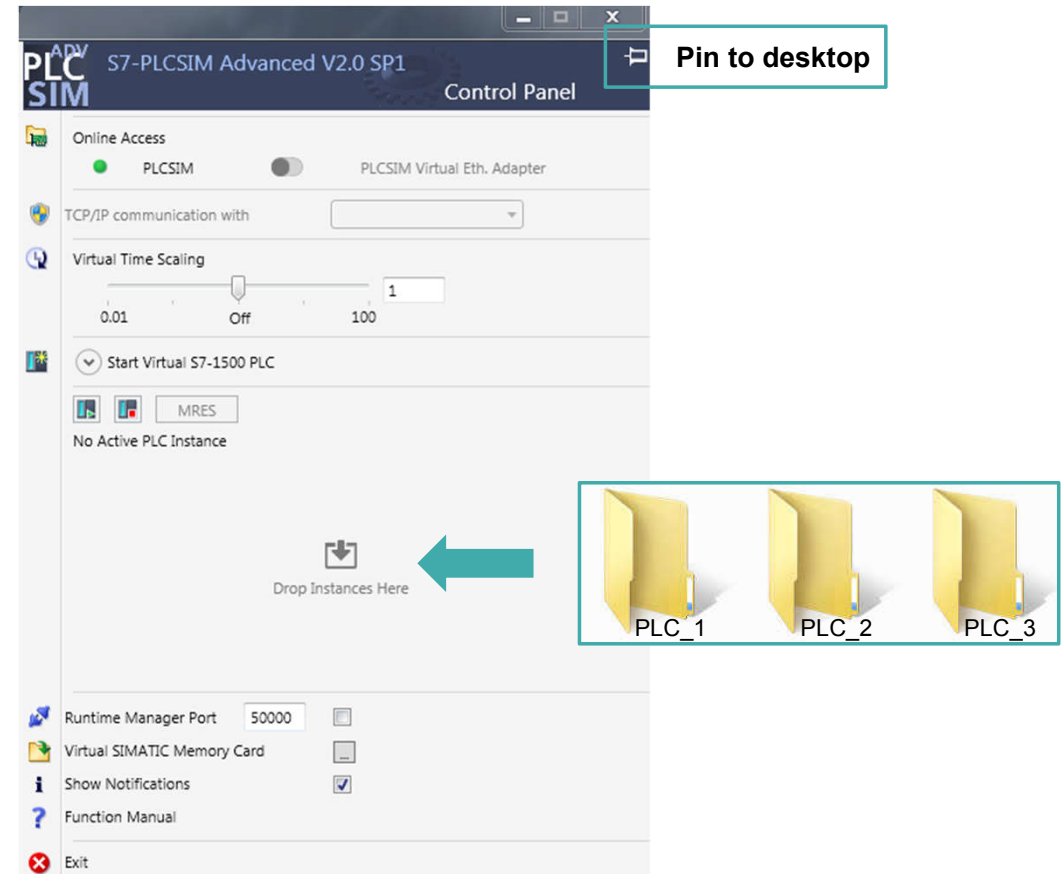
# Highlights V2.0 SP1

# S7-PLCSIM Advanced – Control Panel enhancements

## Function

### The Control Panel can be used in two different ways

- A right-click on the tray icon opens the Control Panel as before (quick view)
- A double left-click on the tray icon opens the Control Panel as a floating window, which allows you to
  - Move the floating window around freely
  - Drag-and-drop instances from an Explorer window to the Control Panel
  - Pin the Control Panel to the desktop (always on top)



# S7-PLCSIM Advanced – Max. cycle time handling through the API

## Function

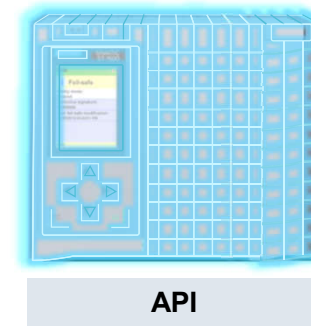
Through the API the maximum cycle time can be either ignored or taken into account, depending on the goal of the simulation

In general there are three operating modes:

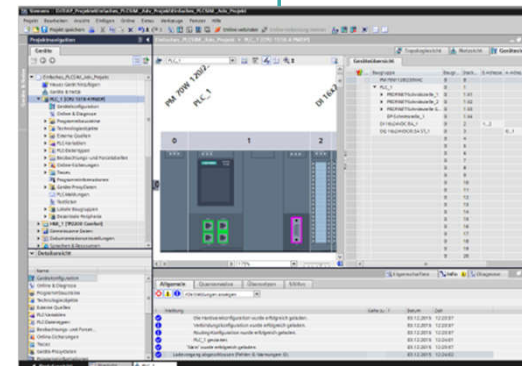
- Ignore the max. cycle time; ignore = 1 minute max. cycle time (default)
- Keep the max. cycle time of the downloaded project
- Define another max. cycle time which can be set through the API

## Customer value

- This feature helps prevent the virtual controller from changing to stop if the max. cycle time is exceeded in a virtual environment.
- No change of the max. cycle time of the TIA Portal project necessary.



**Adapt the max. cycle time  
of the virtual controller through the API**




# Highlights V2.0

# Licensing concept

## Licensing concept overview

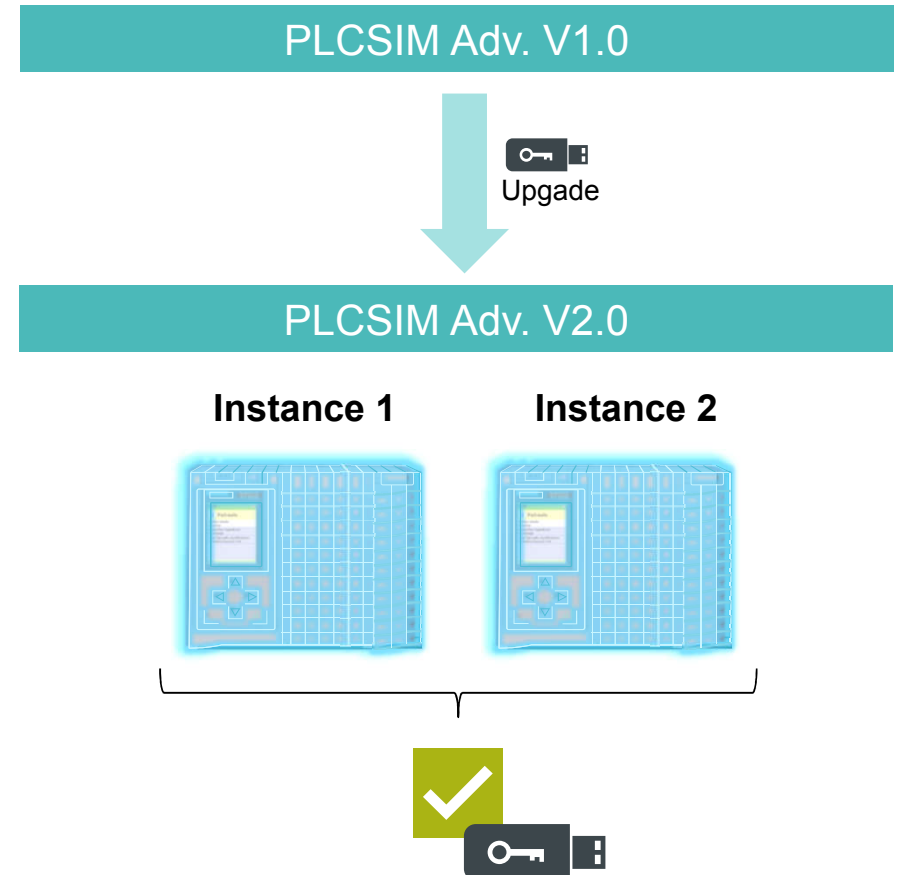
PLCSIM Advanced can be upgraded to the newest version with an upgrade key.

One license enables up to two PLCSIM Advanced  instances on one PC.

### Licensing possibilities:

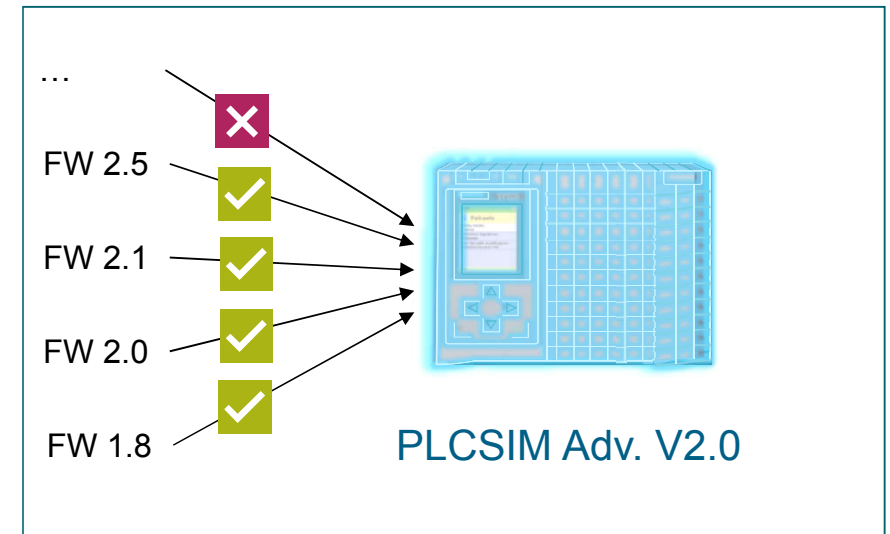
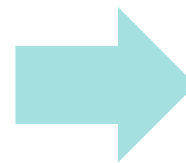
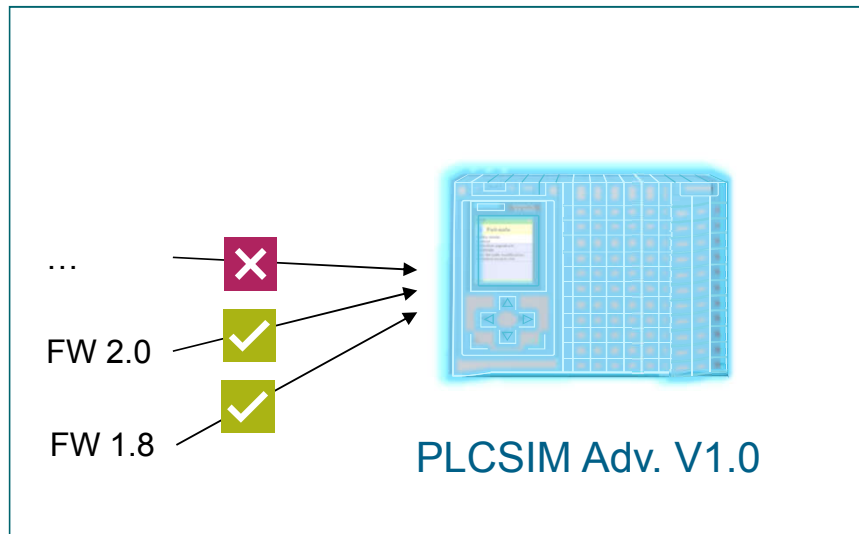
- Floating License
- Trial: free 21 day trial as download:

<https://support.industry.siemens.com/cs/ww/en/view/109754093>



## Supported firmware

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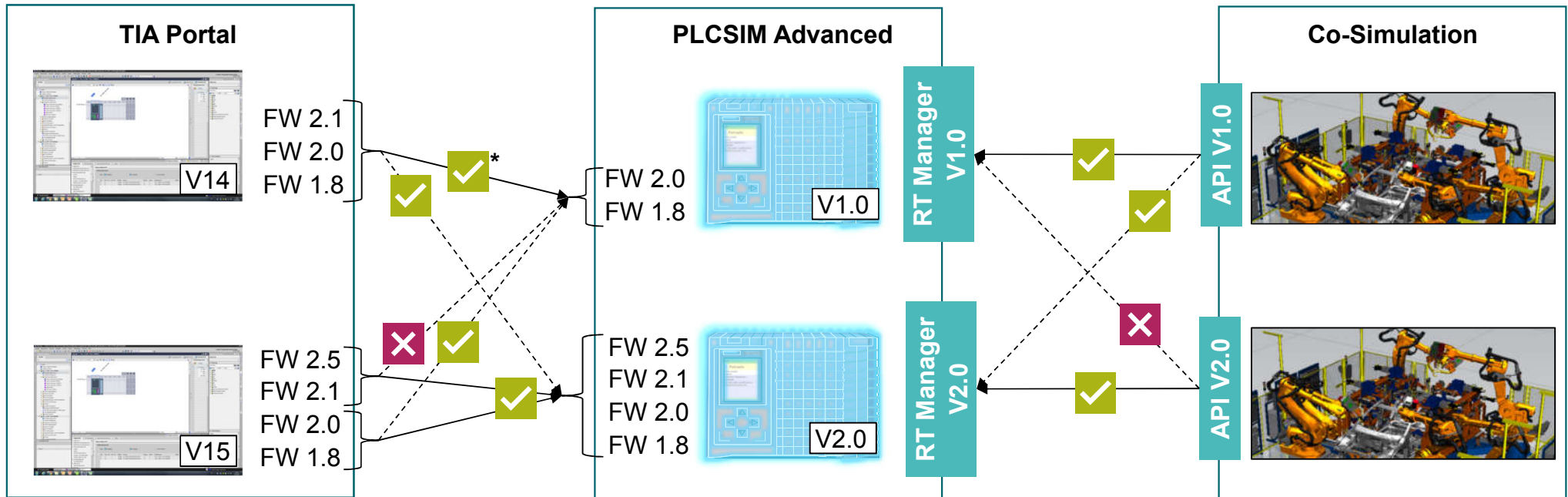


### Strategy

PLCSIM Adv. V2.0 supports the firmware 2.5 which was released with TIA Portal V15 and all earlier firmware releases up to firmware 1.8.

Higher firmware versions will be supported with future PLCSIM Advanced versions adequately.

# Compatibility



## Compatibility to TIA Portal and API versions

- PLCSIM Adv. V1.0 (SP1) and V2.0 are both compatible to TIA Portal V14 (SP1) and V15 as long as the firmware used in TIA Portal is supported by PLCSIM Advanced
- PLCSIM Advanced V2.0 supports both APIs: V1.0 and V2.0



# Synchronisation at Process Image Parts

Synchronisation can take place at a cycle control point and / or at a process image part

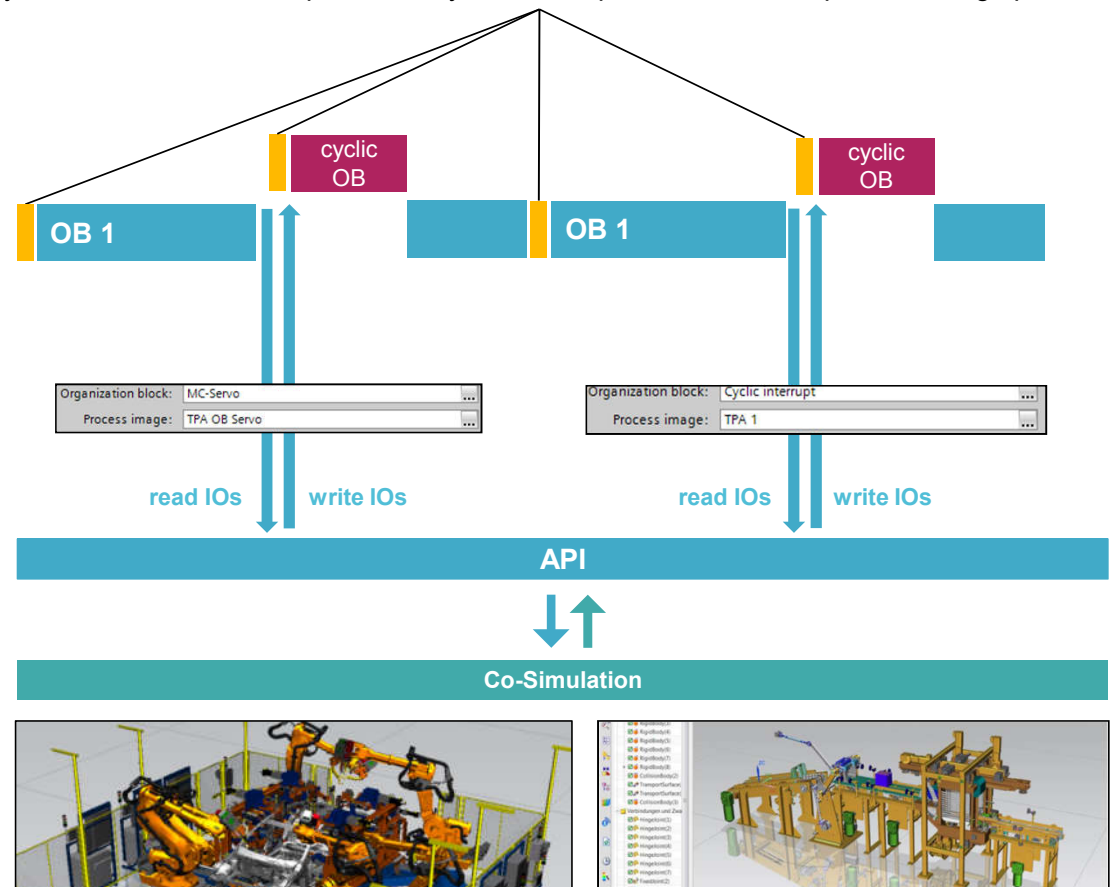
## Synchronisation at Process Image Parts

through the API of PLCSIM Advanced with Co-Simulation-Tools when calling cyclic OBs

- through a process image part attached to a cyclic OB (e.g. cyclic interrupt, MC Servo)
- In the application program with SFCs

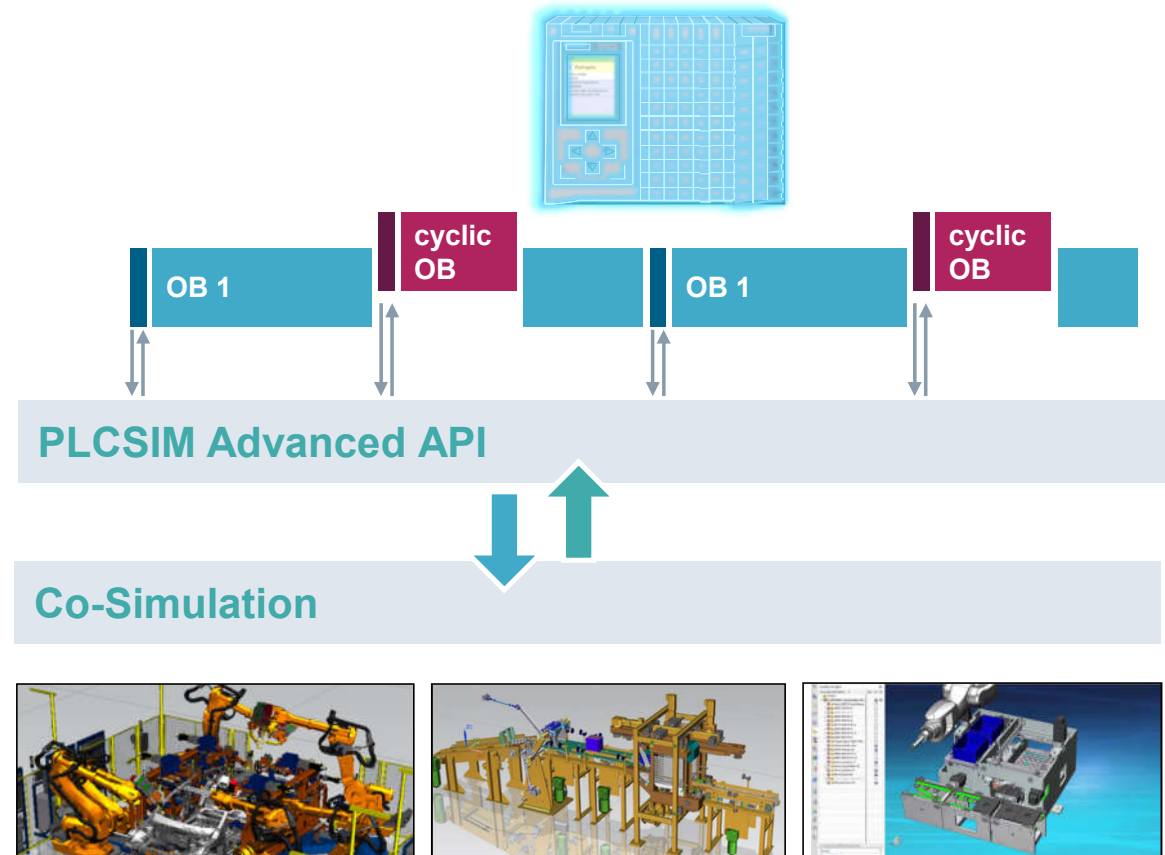
## Advantage

- Verification of the application program including consistent and up to date I/O areas when calling cyclic OBs
- Simulation of Motion Control tasks possible



# Different time-based synchronisation modes in between Co-Simulation and PLCSIM Advanced

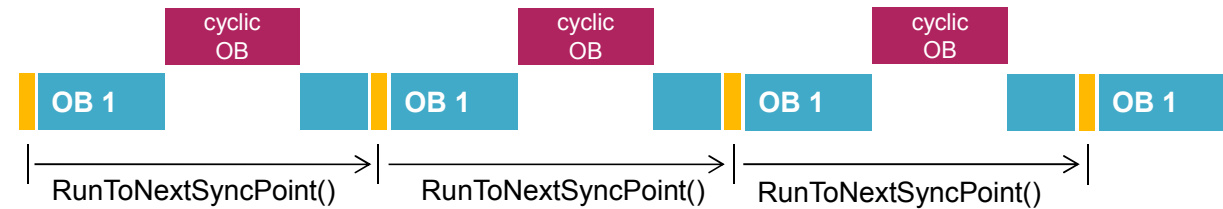
- **Synchronization modes:**
  - synchronization at each cycle control point (beginning of OB1)
  - synchronization at each cyclic OB
  - synchronization at each cycle control point and each cyclic OB
  - Timespan mode: after a defined timespan x the synchronization takes places at the next cycle control point and / or cyclic OB



## Synchronisation – different modes (1/4)

### Operating Mode: Single Step C / CT

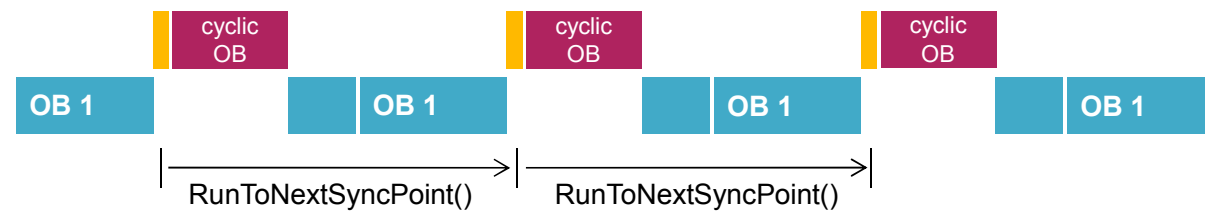
- Single Step C (cycle control point):  
SROM\_SINGLE\_STEP\_C = 1
- Single Step CT (cycle control point; minimal cycle time overwritten):  
SROM\_SINGLE\_STEP\_CT = 2



## Synchronisation – different modes (2/4)

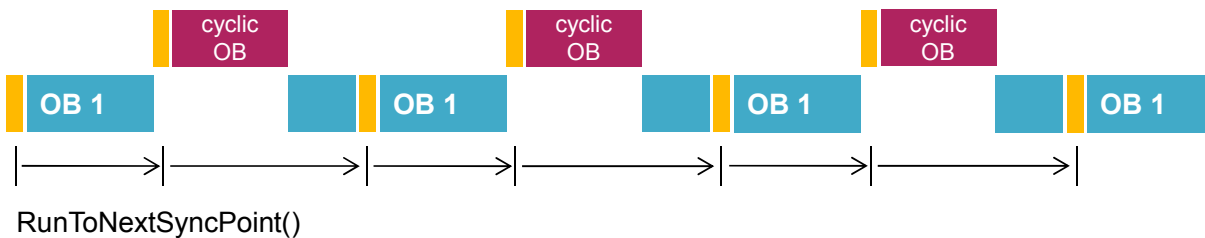
### Operating Mode: Single Step P

- Single Step P (process image part):  
SROM\_SINGLE\_STEP\_P = 4



### Operating Mode: Single Step CP / CPT

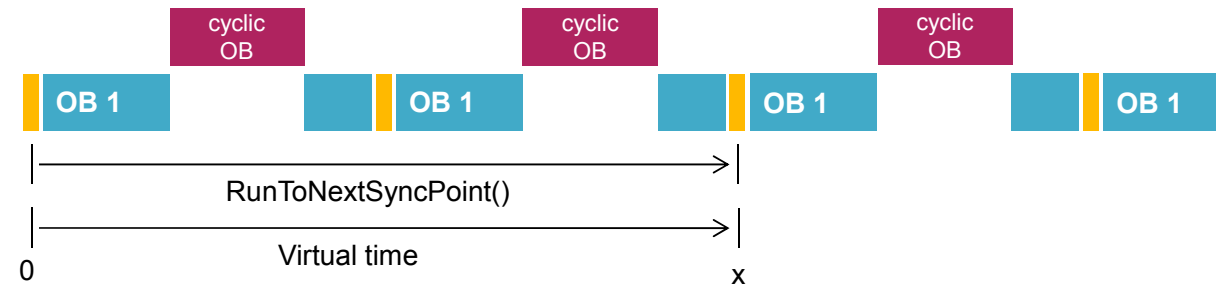
- Single Step CP (cycle control point & process image part): SROM\_SINGLE\_STEP\_CP = 6
- Single Step CPT (cycle control point & partial process image part; minimal cycle time overwritten): SROM\_SINGLE\_STEP\_CPT = 7



## Synchronisation – different modes (3/4)

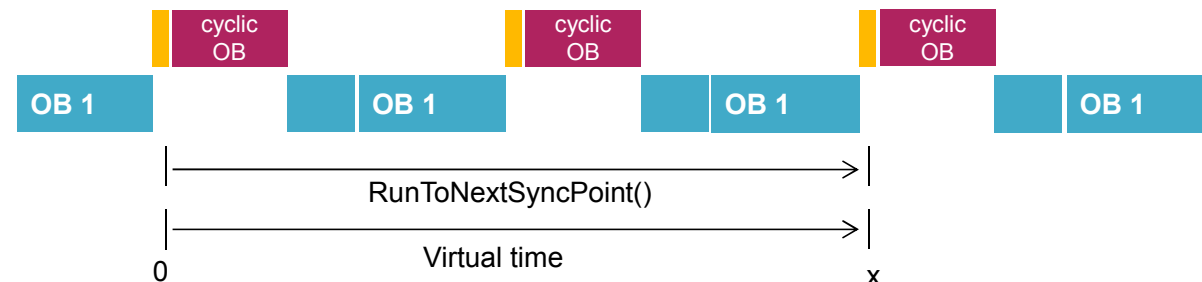
### Operating Mode: Timespan Synchronized C

- Timespan Synchronized C (cycle control point):  
SROM\_TIMESPAN\_SYNCHNRONIZED\_C = 3
- „RunToNextSyncPoint“ will continue to run the simulation until the virtual time x is reached – after the time x is reached the I/O data will be exchanged at the next cycle control point



### Operating Mode: Timespan Synchronized P

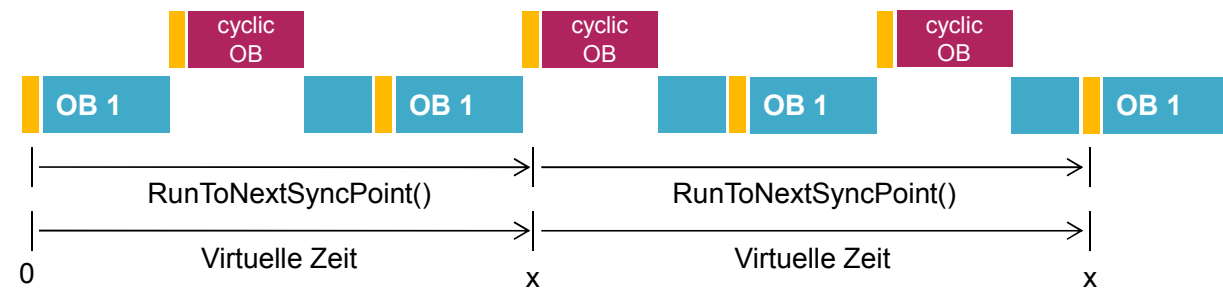
- Timespan Synchronized P (process image part):  
SROM\_TIMESPAN\_SYNCHNRONIZED\_P = 5
- „RunToNextSyncPoint“ will continue to run the simulation until the virtual time x is reached – after the time x is reached the I/O data will be exchanged at the next cyclic OB



## Synchronisation – different modes (4/4)

### Operating Mode: Timespan synchronized CP

- Timespan Synchronized CP (cycle control point & partial process image update):  
SROM\_TIMESPAN\_SYNCHRONIZED\_CP = 8
- „RunToNextSyncPoint“ will continue to run the simulation until the virtual time x is reached – after the time x is reached the I/O data will be exchanged either at the next cyclic OB or the next cycle control point



# Support of acyclical services and alarms

## Acyclical services

- Support of read and write actions of parameter data through SFB52 (RDREC) and SFB53 (WRREC).

## Triggering alarms through the API

Different alarms can be triggered through the API:

- Hardware interrupt (OB40)
- Status Alarm (OB55)
- Update Alarm (OB56)
- Profile Alarm (OB57)
- Diagnostic error interrupt (OB82)
- Pull or plug of modules (OB83)
- Rack or Station failure (OB86)

```
public struct SPlcSimDiagItems  
{  
    public UInt16      ChannelNumber;  
    public UInt16      ErrorType;  
    public UInt16      ExtendedErrorType;  
    public EDiagSeverity Severity;  
    public EDiagProperty Direction  
}
```

**C#**

## Advantage

- Possibility to exchange acyclic data of external modules (central or decentral periphery) in between a co-simulation tool and the PLCSIM Advanced API (e.g. PROFINET diagnosis/status data, RFID data)
- Test of what happens when spontaneous errors occur in a plant/machine

# Read in TIA Portal configured hardware interrupts through the API

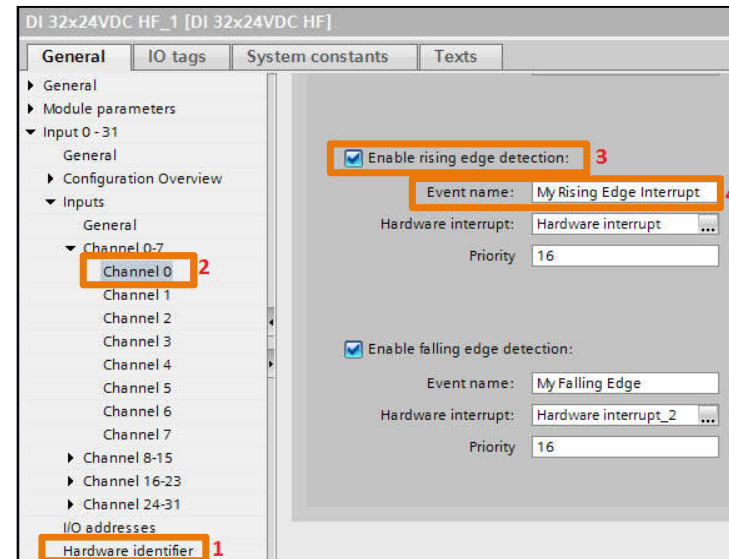
## Read hardware interrupts through the API

*GetConfiguredProcessEvents*: a list of all in TIA Portal configured hardware interrupts (OB40) can be accessed through the API with the following information:

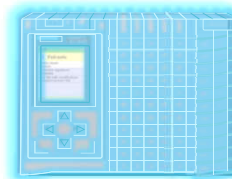
- 1) HardwareID
- 2) Channel number
- 3) Event type
- 4) Name

## Advantage

- A TIA Portal expert and a simulation expert can work independently from each other
- The accessed hardware interrupts can be easily integrated into the Co-simulation tool



When downloading a PLCSIM Advanced instance, the hardware interrupts are part of the download and therefore can be accessed through the API



`GetConfiguredProcessEvents()`

**C#**



## Supported organization blocks

Internal program OBs	V1.0	V2.0
Main (OB1)	✓	✓
Startup (OB100)	✓	✓
Time delay interrupt (OB20)	✓	✓
Cyclic interrupt (OB30)	✓*	✓
Time error interrupt (OB80)	✓	✓
Programming error (OB121)	✓	✓
IO access error (OB122)	✗	✓
MC-Interpolator (OB92)	✓	✓
MC-Servo (OB91)	✓	✓
Synchronous OB(OB61)	✓	✓

Can be triggered by the API	V1.0	V2.0
Hardware interrupt (OB40)	✗	✓
Diagnostic error interrupt (OB82)	✗	✓
Pull or Plug of modules (OB83)	✗	✓
Rack or station failure (OB86)	✗	✓
Status alarm (OB55)	✗	✓
Update alarm (OB56)	✗	✓
Profile alarm(OB57)	✗	✓

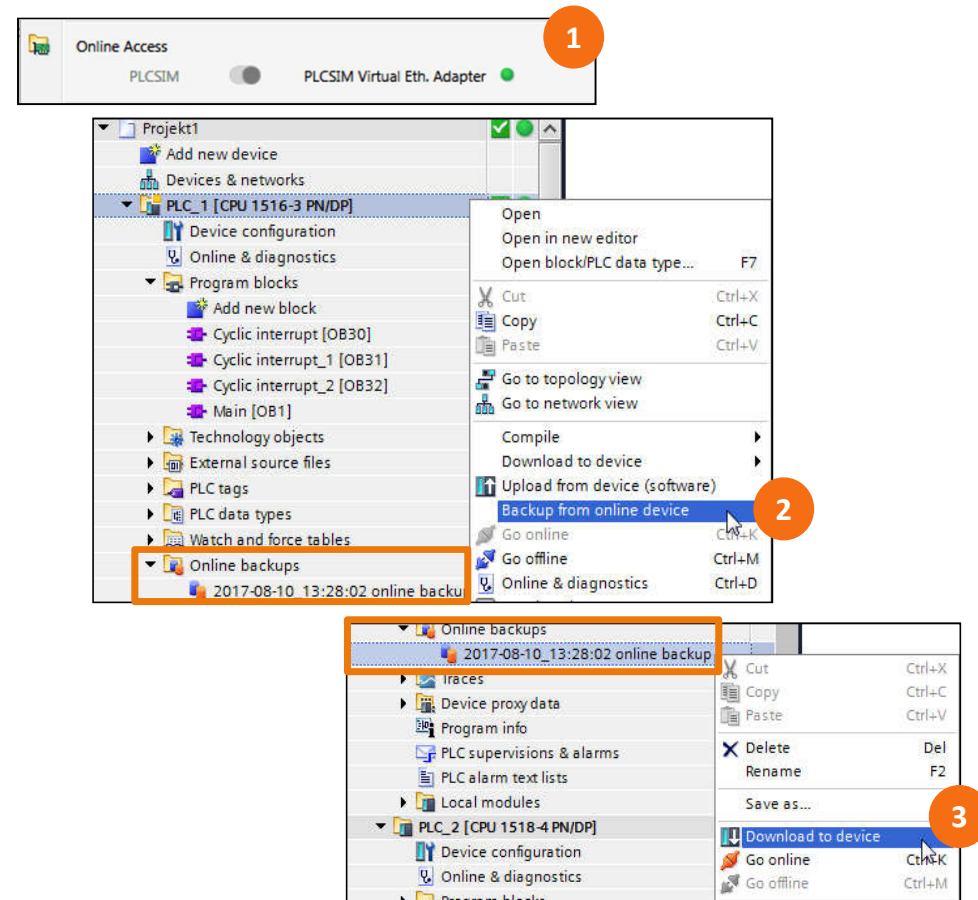
# Backup and restore of software and hardware configuration

## Backup from online device

- Backup of the software- and hardware configuration of a PLCSIM Advanced controller in TIA Portal incl. remanent actual values
- Restore of a backup of the software and hardware configuration into a PLCSIM Advanced instance through TIA Portal
- Pre-requisite: Online Access is set to PLCSIM Virtual Eth. Adapter

## Advantage

- A simulation can be paused and resumed with the backed up data



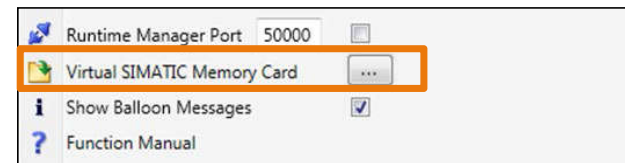
# Individual storage path of the virtual SIMATIC Memory Card

## Individual storage path

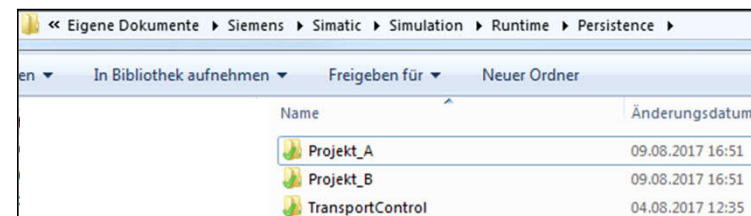
- As soon as a virtual controller is started in PLCSIM Advanced a virtual SIMATIC Memory Card is being created. The storage path of this virtual Memory Card can be chosen freely.
- Pre-requisite: no instance of PLCSIM Advanced is running  
→ As soon as an instance is started the chosen storage path is valid for all instances created afterwards

## Advantage

- Virtual SIMATIC Memory Cards can be saved per project



A click on the box next to „Virtual SIMATIC Memory Card“ opens up the windows explorer where you can choose the storage path



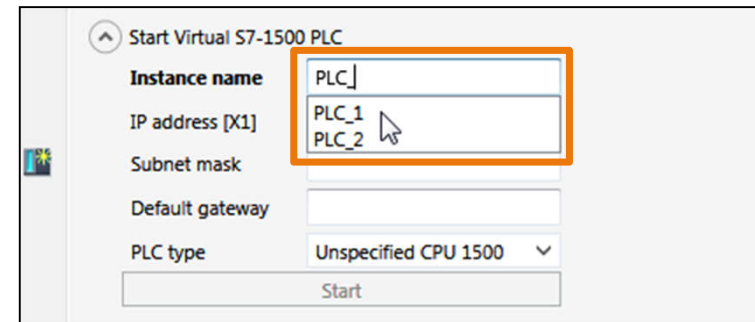
## GUI Enhancements: Auto-fill

### Detection of known controllers

- If a controller was already created in the past, a drop-down menu will be displayed when starting to enter the name of this already known controller. From this drop down menu you can select the appropriate controller (wildcard search) and start it immediately.

### Advantage

- Once defined controllers can be found easily and started quickly.



Start Virtual S7-1500 PLC

Instance name: PLC\_

IP address [X1]:

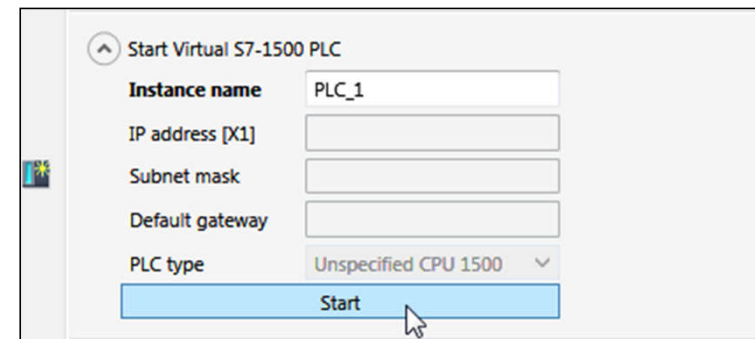
Subnet mask:

Default gateway:

PLC type: Unspecified CPU 1500

Start

If the name of the controller is already known the field below will get greyed-out (IP Adresse, subnet mask, default gateway) and the start button will get active.



Start Virtual S7-1500 PLC

Instance name: PLC\_1

IP address [X1]:

Subnet mask:

Default gateway:

PLC type: Unspecified CPU 1500

Start

# GUI Enhancements: RUN / STOP and Memory Reset

## Change the CPU state to Run/Stop

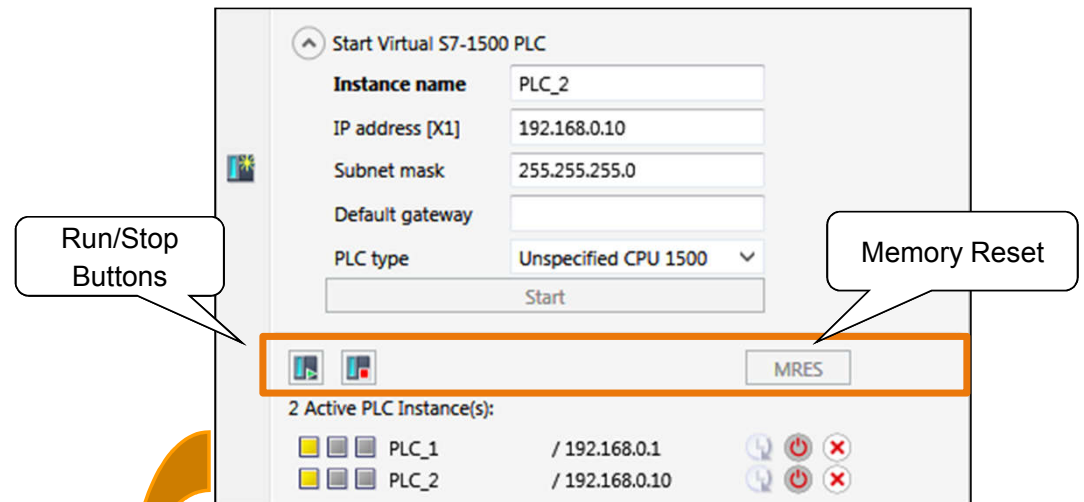
- Change the CPU state of one or more controllers to run/stopp directly in the GUI.

## Perform a Memory Reset

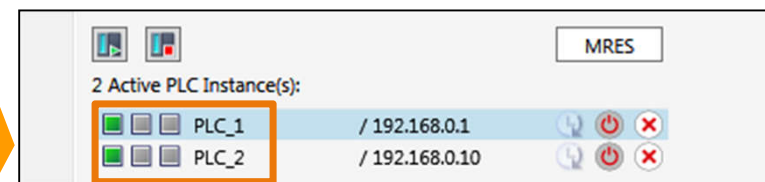
- Perform a memory reset of one or more controllers directly in the GUI.

## Advantage

- Quick and intuitive change of the state of the controllers.
- Easy possibility to perform a memory reset to bring the controllers into a well known and defined state.



Selection of both controllers and click on Run / Stop / MRES



LEDs display the current status of the controllers

## Some more helpful functional enhancements (1/2)

### Independence of the Windows Scheduler

- Leads to a higher performance and a more reliable
  - deterministic
  - simulation of Motion Tasks
- *hint: Windows needs one core and each instance within PLCSIM Advanced needs another core*

### Getting access to SIMATIC virtual memory cards through the API

- The virtual SIMATIC Memory Card can be transferred through the API from one PC to another
- *ArchiveStorage*: saves the SIMATIC Memory Card in a .zip format
- *Retrieve Storage*: rebuilds the SIMATIC Memory Card out of the saved.zip data

.Net (C#)	
Syntax	<pre>void ArchiveStorage(     string in_FullFileName );</pre>
Parameter	<ul style="list-style-type: none"><li>• <b>string in_FullFileName</b>: the full file path to the .zip file. The path is based on the directories of the computer the API is being called.</li></ul>

.Net (C#)	
Syntax	<pre>void RetrieveStorage (     string in_FullFileName );</pre>
Parameter	<ul style="list-style-type: none"><li>• <b>string in_FullFileName</b>: the full file path to the .zip file. The path is based on the directories of the computer the API is being called.</li></ul>

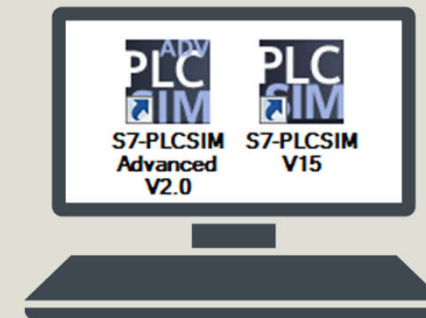
## Some more helpful functional enhancements (2/2)

### Performance enhancements when using symbolic addressing

- Symbolic addressing and direct addressing are adequate in their performance

### Installation of PCLSIM and PLCSIM Advanced on the same PC

- PLCSIM V15 and PLCSIM Advanced V2.0 can be installed on the same PC. A concurrent use of both simulation tools at the same time is not possible.



Thank you for your attention!

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## PLCSIM Advanced Team

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