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Engineered with TIA Portal

SIMATIC S7-1500 T-CPU

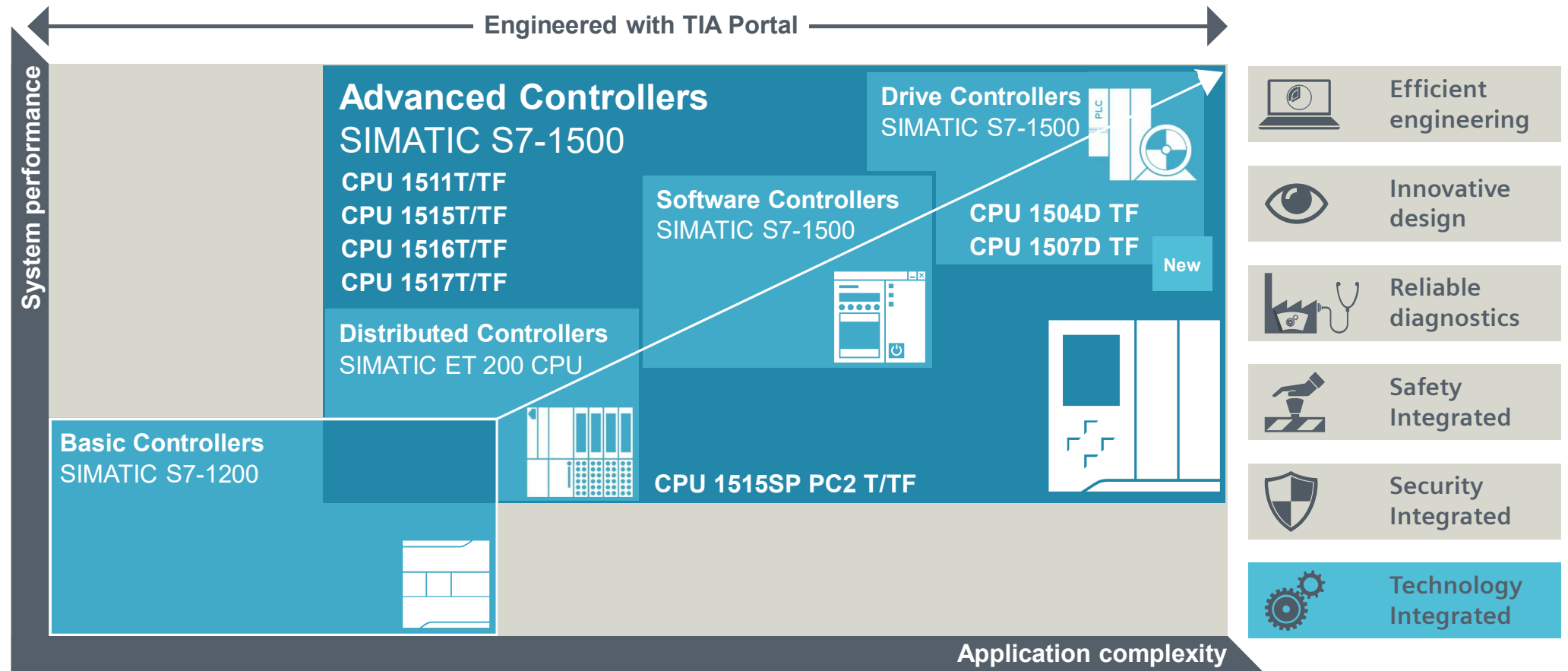
Agility in machine building

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The SIMATIC Controllers Portfolio

Always the right controller – Plus integrated added value!



Advanced Controller – SIMATIC S7-1500 CPU

Increase productivity with the ultimate power

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Security Integrated

- Integrated copy and know-how protection function protect intellectual property
- Improved access protection (authentication)



Safety Integrated

- A controller for standard and fail-safe tasks
- The high-density channel can be directly addressed during the engineering



High Performance

- Higher productivity and product quality thanks to the backplane bus and shortest reaction times
- PROFINET with deterministic time response ensure reproducibility and precision within μ s



Efficient Engineering

- Support of all IEC 61131-3 programming languages (LAD/FBD, STL, SCL and Graph) and of high-level languages such as C/C++ (only for CPU 1518(F)-4 PN/DP MFP and CPU 1515SP PC2 (F/T/TF) through SIMATIC ODK 1500S)



Reliable diagnostics

- The automatic generation of system and user diagnostics enables quick error detection
- Any errors can be quickly localized on-site thanks to 1:1 LED channel assignment for peripheral systems



Technology Integrated

- Motion Control task can be programmed directly in the controller, e.g.
 - Speed-controlled axes, positioning axes, gearing, camming
 - Control of kinematics
 - Cross-PLC synchronous operation
- Implement various technology functions directly with I/O modules (e.g. PWM)



Advanced Controller – SIMATIC S7-1500 T-CPU

Extended motion control functions with TIA Portal V16 and firmware V2.8 ¹⁾

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Additional motion control functions +

- Kinematic functions
 - Control of kinematics with up to 4 interpolating axes
- Gearing and camming
 - Synchronization with specifying the synchronous pos. of the leading and following axes
 - Setpoint value coupling
 - Actual value coupling with extrapolation
- **Cross-PLC synchronous operation** New
 - Synchronisation between axes on different CPUs
- SIMATIC Safe Kinematics V1.0
 - Optional fee-based system library for safe motion monitoring in the cartesian space

Integrated editors and viewers +

- Cam editor
- Kinematics configuration
- Kinematics trace
- Coordination of traces in different CPUs



Hardware innovations +

- SIMATIC S7-1500 T-CPU's
 - CPU 1511T, CPU 1511TF
 - CPU 1515T, CPU 1515TF
 - CPU 1516T, CPU 1516TF
 - CPU 1517T, CPU 1517TF
 - CPU 1515SP PC2 T/TF
 - **CPU 1504D TF, CPU 1507D TF** New
- Standard-, safety-plc and motion control on one controller

Programming +

Consistent and seamless extension of S7-1500 by S7-1500 T-CPU

Web server +

Diagnostic pages for motion control

¹⁾ Compared to the standard CPU

Advanced Controller – SIMATIC Drive Controller

Scalable motion control in the Advanced Controller portfolio

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Ultra-compact Design

- S7-1500 TF-CPU and SINAMICS S120 drive control in one device
- No additional space required for the PLC



Easy scalable

- Uniform interfaces across all performance classes (CPU 1504D TF / CPU 1507D TF)
- Additional drive systems (e.g. SINAMICS S120, S210) can be connected via PROFINET.



Powerful

- Powerful TF-CPU with integrated SINAMICS S120 drive control
- Well equipped with memory, interfaces and technology I/Os

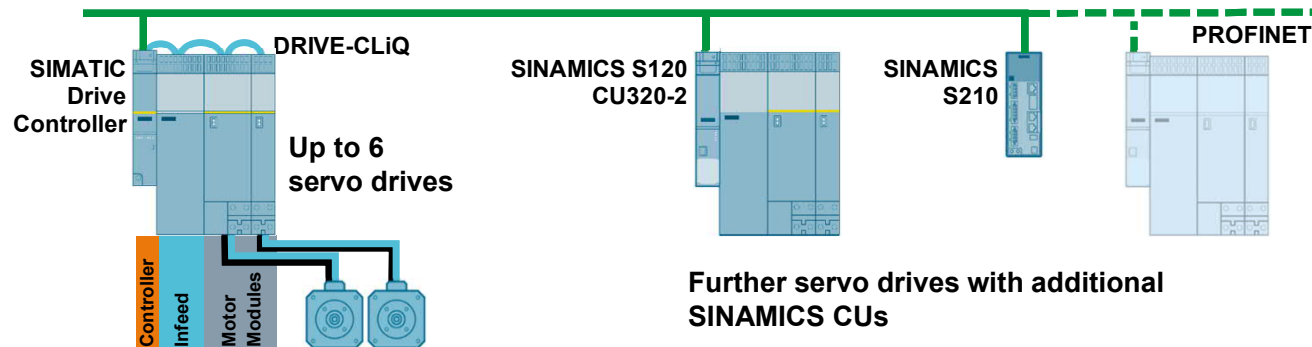


Easy to use

- Comfortable project planning in the TIA portal with SIMATIC STEP 7 and SINAMICS Startdrive
- Low cabling and installation expense
- Central data storage on “one” SIMATIC Memory Card



New



Advanced Controller – SIMATIC S7-1500

Enlargement of the CPU Portfolio with Technology CPUs



	Technology CPU				Standard CPU	Open Controller	Drive Controller CPU	
CPU types	1511TF-1 PN	1515TF-2 PN	1516TF-3 PN/DP	1517TF-3 PN/DP	1518F-4 PN/DP (MFP) ¹	1515SP PC2 TF PN	1504D TF	1507D TF
Interfaces								
Program memory	225/225 KB	750/750 KB	1,5/1,5 MB	3/3 MB	4/6 MB	1/1,5 MB	2 MB	6 MB
Data memory	1 MB	3 MB	5 MB	8 MB	20 MB ¹	5 MB	4 MB	20 MB
Bit performance	60 ns	30 ns	10 ns	2 ns	1 ns	10 ns	Scale with motion control performance	
Functions	Display, S7-1500 backplane bus						SINAMICS S120 Integrated (incl. 12 DI, 8 DI/DQ) additional PLC technology I/Os (8 DI/DQ)	
Positioning axes								
▪ Typical ²	5	7	55	70	128	30	10	55
▪ Maximum ³	10	30	80	128	128	30	30	160
Motion Control Resources ⁴	800	2.400	6.400	10.240	10.240	2.400	2.400	12.800
Extended Motion Control Resources ⁵	40	120	192	256	–	120	120	420

NEW

¹ 50 MB add. for C/C++ (PLC-RT)+500 MB for C/C++ appl. (RT/appl.)

⁴ Resources for Motion Control technology objects:

⁵ Resources for Extended Motion Control technology objects:

² At 4 ms Servo/IPO cycle time and 35 % CPU load due to Motion Control

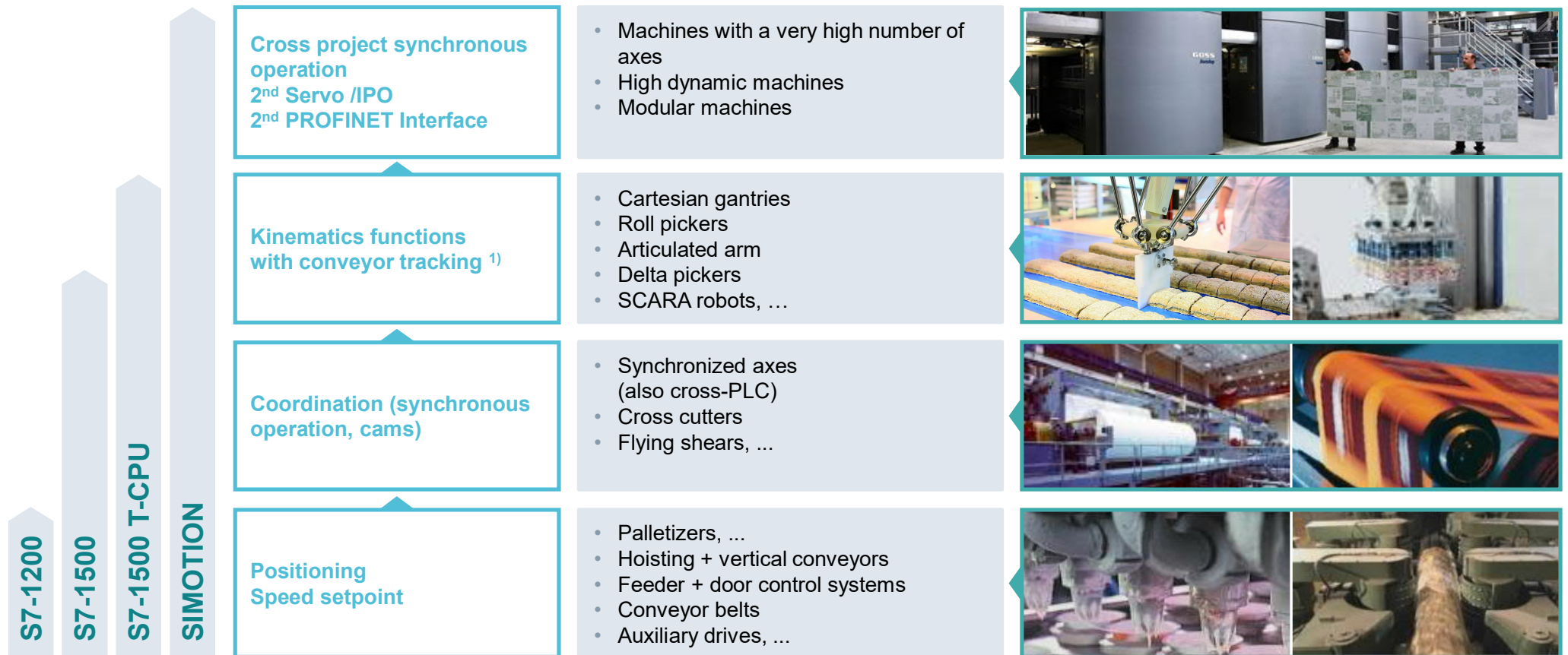
Speed axis = 40 | Positioning axis = 80 | Synchr. Axis = 160 | Output cam= 20 | Output cam track= 160 | Measuring input= 40
Cams = 2 | Kinematic objects= 30 | Leading axis proxy = 3

³ No further TO's applicable

1 PROFINET IO with IRT **2** PROFINET IO with RT **3** PROFINET basic communication (1 Gbit) PROFIBUS

Overview

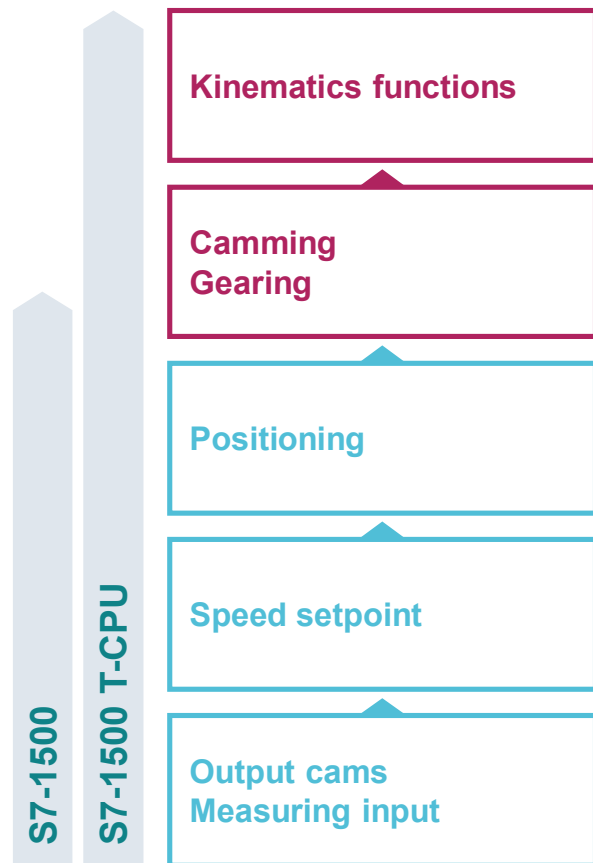
Motion control functions and typical applications



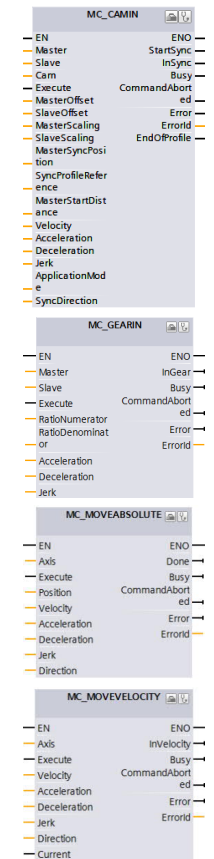
¹⁾ planned for FW-Update V2.8.x (V16)

Advanced Controller – SIMATIC S7-1500

Overview motion control functionalities (extract)

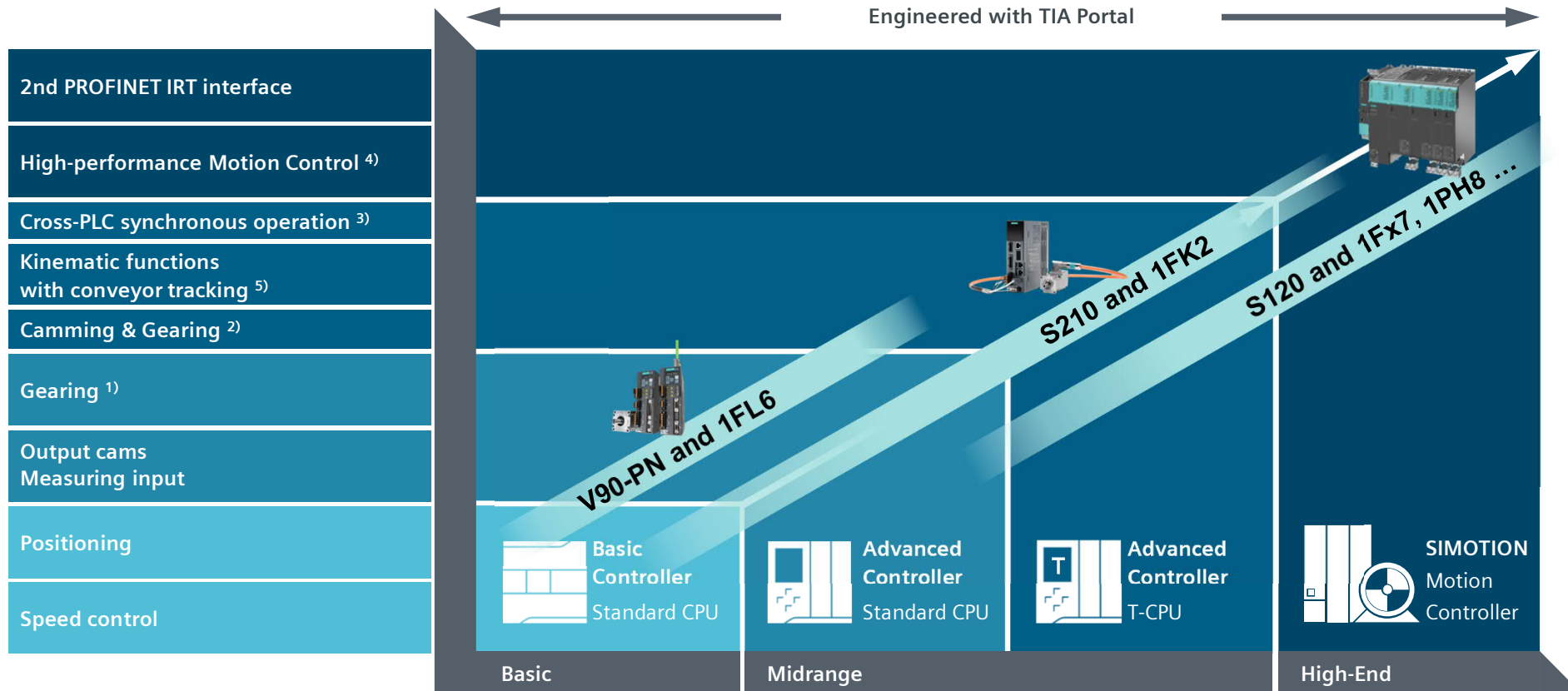


- Kinematics with conveyor tracking¹⁾ **New** (T-CPU only)
- Kinematics with up to 4 interpolating axes (T-CPU only)
- Cross-PLC synchronous operation **New** (T-CPU only)
- Offset of the leading value at the following axis (T-CPU only)
- Camming (T-CPU only)
- Coupling onto actual values (T-CPU only)
- Gearing - With synchronous position (T-CPU only)
- Gearing - Without synchronous position (T-CPU only)
- Encoder switch over to 2nd – 4th encoder (T-CPU only)
- Specification of motion vector from application (T-CPU only)
- Superimposed positioning during active motion
- Move axis to relative/absolute position
- Cyclic interface for torque data
- Moving an axis with torque limiting
- Homing absolute and on the fly, Setting a position
- Traversing an axis with speed setpoint
- Enabling/disabling an axis
- Activating output cams and cam tracks and measuring inputs
- ...



TIA Portal V16

The scalable Motion Control System Portfolio



¹⁾ Synchronization without specification of the synchronous position

³⁾ In one project

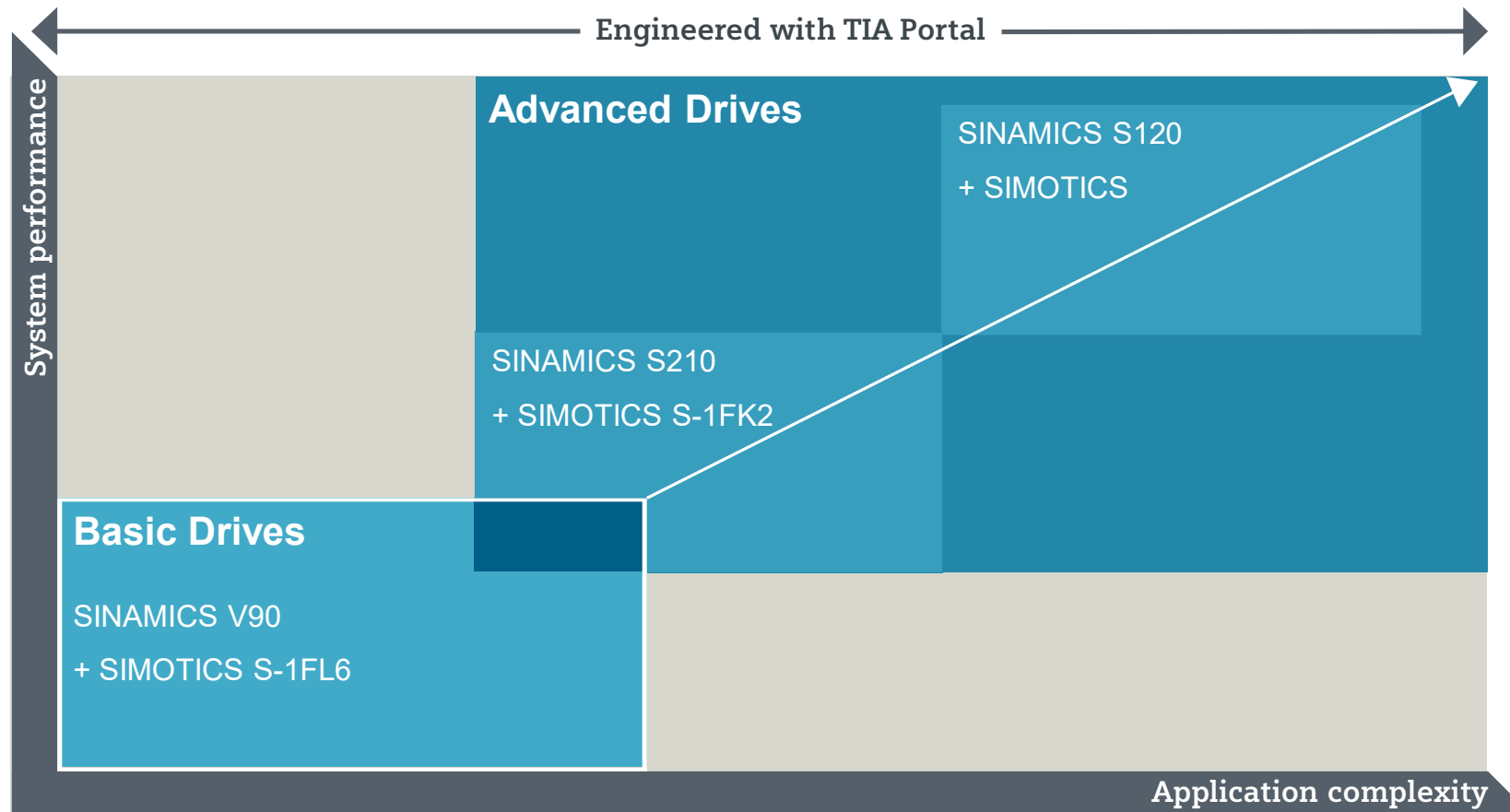
²⁾ Synchronization with specification of the synchronous position

⁴⁾ Cross-project synchronization; cams with dynamic size; 2 servo for axis groups

⁵⁾ planned for FW-Update V2.8.x (V16)

The SINAMICS Drives Portfolio for “Cyclic Motion”

Always the right drive – Plus integrated added value!



-  Consistent drive and automation solutions
-  Seamless interaction of all drive components
-  Optimum maintenance and service
-  Safety Integrated
-  Technology Integrated

Questions and Answers

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Hvala na pažnji

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