

## 7SJ551 multi-function protection relay

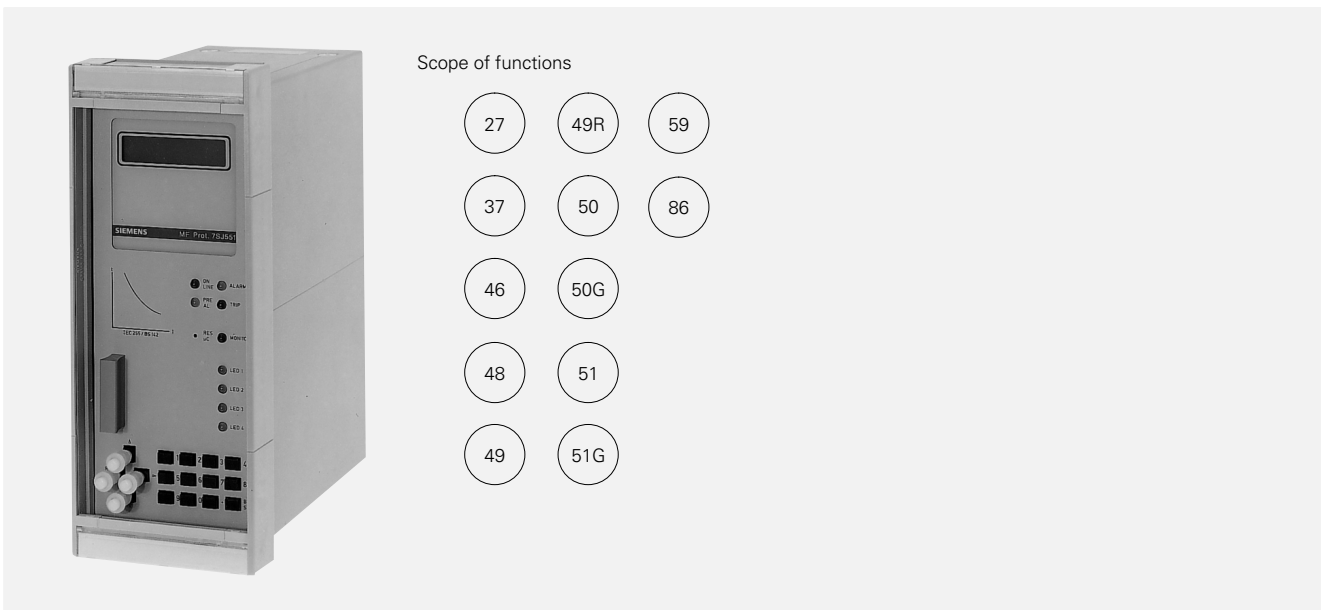


Fig. 1  
7SJ551 multi-functional protection relay

### General

- The numerical multi-function protection relay is a fully microprocessor based relay of the 7S-relay family.
- The relay can be integrated into station control systems like the LSA system via a serial communication interface with an internationally standardized protocol.

### Application

- Multi-function protection relay for rotating electric machines, especially asynchronous motors
- Thermal overload, overcurrent and earth-fault protection for transformers and cables
- Back-up protection for differential and distance relays in high voltage feeder protection schemes
- Earth-fault direction protection for isolated, compensated and high-ohmic earthed networks
- Directional overcurrent and earth-fault protection in combination with external connected directional unit like 7SP20

### Implemented functions/features

- Thermal overload protection of rotating devices:
  - separate thermal replica for stator and rotor based on True RMS current measurement
  - up to 2 heating time constants for the stator thermal replica
  - separate cooling time constants for stator and rotor thermal replica
  - ambient temperature biasing of thermal replica
  - incorporation of additional heating effects of asymmetrical currents.
- Thermal overload protection of non-rotating devices:
  - up to 2 heating time constants with extremely wide setting ranges for optimal thermal protection of cables and transformers
  - externally adjustable time constant
  - ambient temperature biasing of thermal replica.
- Connection of up to 8 RTD sensors.
- Multi-curve overcurrent and earth-fault protection:
  - insensitive for transients and DC components
  - separate two stage tripping characteristics for phase and earth elements
- four selectable internationally standardized (BS 142, IEC 255-4) tripping characteristics for phase elements: Normally Inverse, Very Inverse, Extremely Inverse and Definite Time
- two additional tripping characteristics for the earth element: Long Time Earth-fault and Residual Dependent Time
- customized curves instead of standard curves can be programmed to offer optimal flexibility for both phase and earth elements
- Curve Switch and Blocking functions offer an adaptive feature to change the relay characteristics according to prevailing system conditions
- Separate setting tables for the protection of rotating and non-rotating network components
- Equipped with highly sophisticated protection algorithms which offer optimal flexibility in grading with other protection relays and with the thermal limit curves of primary components
- Software matrix for signalling and tripping relays
- Real Time Clock: last 3 events are stored with real time stamps of alarm and trip data
- Fault recording

# Motor Protection

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### Thermal overload (ANSI 49/49R)

The relay uses a thermal memory to resemble the remaining thermal capacity of the protected device. This is a measure for the allowed heating of the protected device. The thermal capacity can be obtained from the True RMS phase currents, taking into account the effect of asymmetrical current.

A pre-alarm signal is issued when the thermal memory reaches the warning level.

### Start inhibit (ANSI 86)

The start inhibit function permits starting of the motor only when the thermal reserve of the motor is sufficient for a complete start.

### Emergency restart

To override the start inhibit condition it is possible to activate an input for the emergency restart function, which leads to a discharge of the thermal memory.

### Ambient temperature biasing

The thermal capacity available can be adjusted according to the actual ambient temperature as monitored by an RTD-sensor.

### Overtemperature

Up to 8 RTD sensors (Pt-100, Ni-100 or Ni-120) can be used to monitor the temperature of the protected device.

### Undercurrent (ANSI 37)

This function is normally used to detect a decrease in current flow caused by a loss of, or decrease in, motor load. This is especially useful for indication of loss of suction of pumps, loss of airflow for fans, or a broken belt for conveyors.

### Low set overcurrent (ANSI 51/51G/51N) and high set overcurrent (ANSI 50/50G/50N)

The "low set overcurrent function" protects against short circuits. The Low Set Overcurrent function can be configured with six different tripping characteristics, which can be set for phase and earth elements independently. The time dependent characteristics are standardized according to IEC 255 and BS 142.

The "high set overcurrent function" protects devices against immediate short-circuits and mechanical jams. Phase and earth elements can be selected independently.

### Unbalance (ANSI 46)

This function protects a device against overheating caused by unequal phase loading. Also breaks, short-circuits and reversed phase current connections can be detected. The sequence of connections can be externally chosen either clockwise or counterclockwise.

### Locked rotor (ANSI 48) and zero speed

To protect a motor with a "locked rotor" the maximum allowable time between a motor start attempt and the beginning of normal running operation can be protected.

When the permissible locked rotor time is less than the starting time the "zero speed" input detects if the rotor is locked during the start attempt.

### Undervoltage (ANSI 27) and overvoltage (ANSI 59/64)

The "undervoltage function" protects devices against operating on too low voltage.

The "overvoltage function" protects devices against operating under too high phase, line or zero sequence voltage.

### External command and breaker failure trip

An external command (e.g. emergency stop button) can issue an immediate or delayed trip command.

The "breaker-failure trip function" is able to issue a second trip command as a back-up facility, when the issued trip command, either by the relay itself or by an other externally connected protection relay, does not lead to a decrease of the measured current flow.

### Directional earth fault (ANSI 67G)

This function is able to detect the direction of the earth fault in those networks where the starpoint is isolated, high-ohmic grounded or grounded by a Petersen coil.

### Curve switch

This function makes it possible to switch from one set of Low Set/High Set Overcurrent setpoints to another when the system conditions have changed.

### Block

Individual trip elements, such as "undercurrent", "undervoltage", "low set and high set overcurrent" can be blocked temporarily.

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### Technical data

<b>Power supply</b>	Supply voltage 24/60 V DC 110/250 V DC Supply voltage 110/230 V AC Battery drain	quiescent energized	19.2 to 88 V 88 to 300 V 88 to 256 V 15 W 20 W
<b>Energizing input circuits</b>	Rated current $I_N$ Rated frequency $f_N$ Thermal withstand Maximum c.t. burden at $I_N$ Rated voltage $V_N$ Rated frequency $f_N$ Thermal withstand Maximum c.t. burden at $V_N$	continuously for 1 sec for 10 sec half cycle continuously	1 or 5 / 1 A 50 / 60Hz 6 x $I_N$ / 4 A 100 x $I_N$ / 75 A 30 x $I_N$ / 20 A 250 x $I_N$ / 200 A 0.1 / 0.2 VA 100 or 110 V 50 / 60 Hz 1.2 x $V_N$ 0.1 VA
<b>External control inputs</b>	Control voltage 24 to 250 V DC 110 to 230 V AC Control current Detection time		19.2 to 300 V DC 88 to 256 V AC typical $\leq 3$ mA 10 msec
<b>Output contacts</b>	2 NO 1 NC 1 NO (5 x) Switching voltage, max. Make and carry Permissible current Switching capacity	continuous make break	Output 1 Monitor Output 2 to 6 300 / 250 V AC max. 30 A / 0.5 sec 5 A max. 1 000 W 30 W / 50 VA
<b>LED displays</b>	Ready for operation Internal fault Thermal overload Protection functions Trip Marshallable LEDs	green red yellow yellow red yellow	ON LINE MONITOR PRE ALARM ALARM TRIP LED 1 to 4
<b>Serial interface</b>	Protocol Transmission speed Safety RS485 transmission distance Fibre optic interface Transmission distance Optical wave length Permissible attenuation		according to IEC 870-5 2400/4800/9600/19200/38400 baud Hamming distance d = 4 1 200m 2 km 820 nm max. 8 dB
<b>Temperature sensors</b>	Suitable for Number Connection terminals Connection cable (to be ordered separately)	max. resistance	Pt 100/Ni 100/Ni 120 2 or 8 3 for each sensor <25 $\Omega$

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<b>Thermal overload</b>	Full load current $I_{flc}$ No load current $I_{noload}$ Start current $I_{start}$ Safety factor $k$ Unbalance factor $k_{inv}$ Cold starts $n_{cold}$ Warm starts $n_{warm}$ Thermal time $\tau_1, \tau_2$ Start time $t_{start}$ Weight factor $p_{weight}$ Accuracy of $I_{flc}$ Accuracy trip time	0.05 to $28 I_N$ 0.05 to $1 I_N$ 0.05 to $28 I_N$ 1 to 1.5 0 to 10 1 to 15 1 to 15 1 sec to 999 min 1 to 200 sec 0 to 1 $\pm 5\%$ $\pm 2\%$
<b>Overtemperature</b>	Alarm level $T_{alarm}$ Trip level $T_{trip}$ Accuracy	0 to 200 °C 0 to 200 °C 1 °C
<b>Undercurrent</b>	Alarm level $I<$ Dead time $t_{bypass}$ Trip time $t I<$ Accuracy of $I<$ Accuracy trip time Drop off/pick up ratio	0.05 to $28 I_N$ 0 to 100 sec 0 sec to 166 min $\pm 5\%$ $\pm 2\%$ 0.95 $\pm$ 0.01
<b>Low set overcurrent on phase and earth</b>		
<b>Definite time</b>	Alarm level $I>$ Alarm level $I_{E>}$ sensitive Time $t I>$ and $t I_{E>}$	0.05 to $28 I_N$ 0.003 to 1.4 A 0 sec to 166 min
<b>Inverse time</b>	Characteristics Alarm level $I_p$ Alarm level $I_{ep}$ sensitive Time factor $t_p$ and $t_{ep}$	NI, VI, EI, LTE, RD BS 142 – 1966 0.05 to $28 I_N$ 0.003 to 1.4 A 0 to 10
<b>Custom curve</b>	Number of points Alarm level $I_x$ Alarm level $I_{ex}$ sensitive Trip time $t I_x$ and $t I_{ex}$ Accuracy $I>/I_p / I_x$ Accuracy trip time Drop off/pick up ratio	2 to 15 0.05 to $28 I_N$ 0.003 to 1.4 A 0 sec to 166 min $\pm 5\%$ $\pm 2\%$ 0.95 $\pm$ 0.01
<b>High set overcurrent on phase and earth</b>	Alarm level $I>>$ Alarm level $I_{E>>}$ sensitive Time $t I>>$ and $t I_{E>>}$ Accuracy of $I>>$ Accuracy trip time Drop off/pick up ratio	0.05 to $28 I_N$ 0.003 to 1.4 A 0 sec to 166 min $\pm 5\%$ $\pm 2\%$ 0.95 $\pm$ 0.01
<b>Unbalance</b>		
<b>Extremely inverse</b>	Alarm level $I_{2p}$ Dead time $t_{bypass}$ Time factor $t_{2p}$ Accuracy of $I_{2p}$ Accuracy trip time Drop off/pick up ratio	0 to $1 I_N$ 0 to 100 sec 0 to 25 $\pm 5\%$ $\pm 2\%$ 0.95 $\pm$ 0.01
<b>Locked rotor</b>	Delay time $t_{lr}$ Accuracy trip time	0 to 200 sec $\pm 2\%$
<b>Undervoltage</b>	Alarm level $V<$ Trip time $t V<$ Accuracy of $V<$ Accuracy trip time Drop off/pick up ratio	0.05 to $1.2 V_N$ 0 sec to 166 min $\pm 5\%$ $\pm 2\%$ 0.95 $\pm$ 0.01

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### Technical data

<b>Overvoltage</b>	Alarm level $V>$ Trip time $t V>$ Alarm level $V>>$ Trip time $t V>>$ Accuracy of $V>$ , $V>>$ Accuracy trip time Drop off/pick up ratio	$0.05$ to $1.2 V_N$ $0$ sec to $166$ min $0.05$ to $1.2 V_N$ $0$ sec to $166$ min $\pm 5$ % $\pm 2$ % $0.95 \pm 0.01$
<b>Breaker failure trip</b>	Alarm level $I_{bf}$ Trip time $t_{bf}$ Accuracy of $I_{bf}$ Accuracy trip time Drop off/pick up ratio	$0.05$ to $28 I_N$ $0$ sec to $166$ min $\pm 5$ % $\pm 2$ % $0.95 \pm 0.01$
<b>Directional earth fault</b>	Setting range Alarm level $I_{\phi>}$ , $I_{\phi p}$ , $I_{\phi>>}$ Alarm level $V_{STRT}$ Trip time $t I_{\phi>}$ , $t I_{\phi>>}$ Time factor $t_{\phi p}$ Angle $\phi_e$	$I_{\phi} \cos \phi$ or $I_{\phi} \sin \phi$ $0.003$ to $1.4$ A $0.05$ to $1.2 V_N$ $0$ sec to $166$ min $0$ to $10$ $-45$ to $+45^\circ$
<b>Reference conditions</b>	Temperature Power supply Line frequency 3rd harmonic 5th harmonic	$-10$ to $+55$ °C $0.8$ to $1.15 \times V_N$ $0.9$ to $1.1 \times f_N$ $10$ % (phase 0/180°) $10$ % (phase 0/180°)
<b>Construction of unit</b>	Case: dimensions (standard metal housing for flush mounting) Weight Degree of protection acc. to EN 60529	7XP20 approx. $4$ kg IP51
<b>Connections</b>	Energizing input circuits, modular terminal blocks  Each terminal features:           1 snap-on connection 1 screw connection  External control inputs, output contacts Each terminal features:           1 snap-on connection 1 screw connection	Heavy duty terminals with shorting facilities $2.5$ mm <sup>2</sup> (# 12 AWG appr.) $4$ mm <sup>2</sup> (# 10 AWG appr.)  $1.5$ mm <sup>2</sup> (# 14 AWG appr.) $1.5$ mm <sup>2</sup> (# 14 AWG appr.)
<b>Dielectric tests, electrical environment immunity</b>	Insulation test IEC 255-5 Impulse voltage IEC 255-5 Insulation resistance IEC 255-5	$2$ kV, $50$ Hz, $1$ min  Test voltage $500$ V DC, withstand test $\geq 100$ M $\Omega$ $1.2/50$ $\mu$ s, $0.5$ J / $5$ kV, $R_i = 500$ $\Omega$ , $5$ kV CM, $5$ kV DM
<b>Disturbance tests</b>	High frequency disturbance (surge withstand capability SWC) IEC-255-6, IEC 255-22-1, Class 3 Electrostatic discharge IEC 801-2, Class 3 Radiated electromagnetic field test IEC 801-3, Class 3 Fast transient test Repetition rate Burst duration Burst period Test duration IEC 801-4, Class 4 Spike test as recommended by KEMA	$1$ MHz CM, $2.5$ kV DM, $1$ kV  $150$ pF, $150$ $\Omega$ , $8$ kV  $0.15$ to $300$ MHz, $10$ V/m  $5/50$ nsec, $R_i = 50$ $\Omega$ $5$ kHz $15$ msec $300$ msec $10$ sec, $4$ kV CM  $0.15/50$ $\mu$ sec, $R_i = 5$ $\Omega$ , DM $1$ kV
<b>Radio interference</b>	EN 55011	$0.15$ to $30$ MHz line interference $30$ MHz to $1$ GHz radiation

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<b>Climatic conditions</b>	Permissible ambient temperature	in service during transport during storage	-10 to +55 °C -25 to +55 °C -25 to +70 °C
	Humidity class according to IEC 68-2-30 Relative humidity		6 cycles/12 hrs, +25/+55 °C, humidity 95 % annual average ≤ 75 % relative humidity on 30 days of the year up to 95 % relative humidity Condensation not permissible
<b>Vibration</b>	IEC 68-2-6, DIN 40 048-8		10 – 55 Hz, 2 g, 20 sweeps, 3 directions
<b>KEMA type test</b>	The relay 7SJ551 has been type tested by KEMA – laboratories in Arnhem, The Netherlands. Type test results are laid down in the reports No. 37469-KCS/LB-93-1017 and 37469-KCS/LB-1036.		

### Selection and ordering data

<b>7SJ551 multi-function protection relay</b>	Order-No. <b>7SJ551</b> □ - □ □ <b>A</b> <b>0</b> <b>0</b> - □ □
Nominal current/frequency R, T, e 1/5 A, 50/60 Hz R, S, T, e 1/5 A, 50/60 Hz R, T 1/5 A, e sensitive 1 A, 50/60 Hz R, S, T 1/5 A, e sensitive 1 A, 50/60 Hz	↑ <b>1</b> ↑ <b>2</b> ↑ <b>3</b> ↑ <b>4</b>
Auxiliary supply voltage 24–60 V DC 110–250 V DC/110–230 V AC	↑ <b>1</b> ↑ <b>2</b>
Construction horizontal module vertical module	↑ <b>A</b> ↑ <b>B</b>
Option A: Connections no option extended I/O: 3 extra inputs, 2 extra outputs, 4 extra LEDs, output 1 doubled extended I/O + voltage functions (single phase) extended I/O + voltage functions (single phase) + directional earth-fault protection (only in combination with e sens. 1 A)	↑ <b>0</b> ↑ <b>1</b> ↑ <b>2</b> ↑ <b>3</b>
Option B: Interfaces no option RS-485 + optical interface RS-485 + optical interface + connection for 2 RTD sensors RS-485 + optical interface + connection for 8 RTD sensors	↑ <b>A</b> ↑ <b>B</b> ↑ <b>C</b> ↑ <b>D</b>

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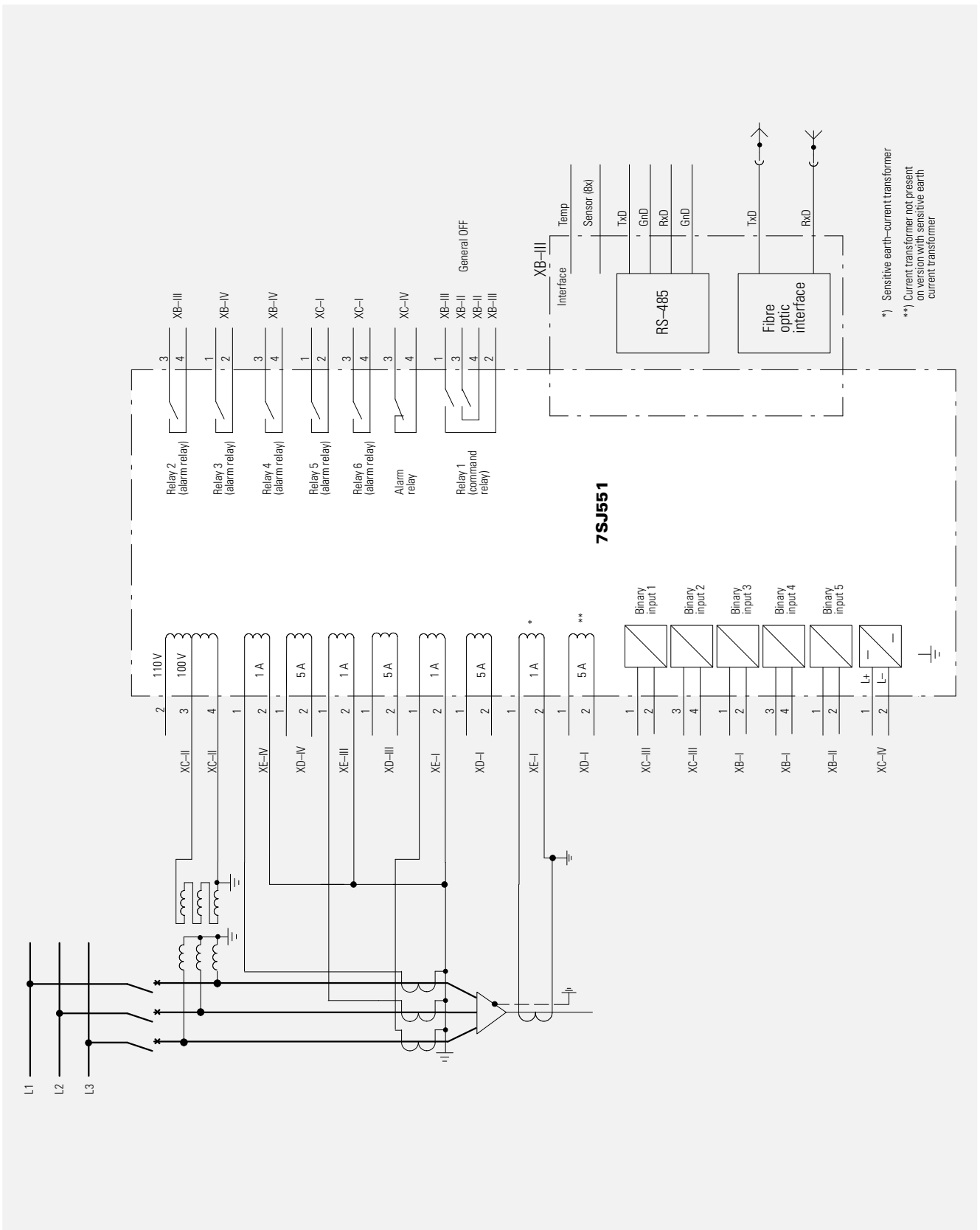


Fig. 2  
Application feeder protection

# Motor Protection

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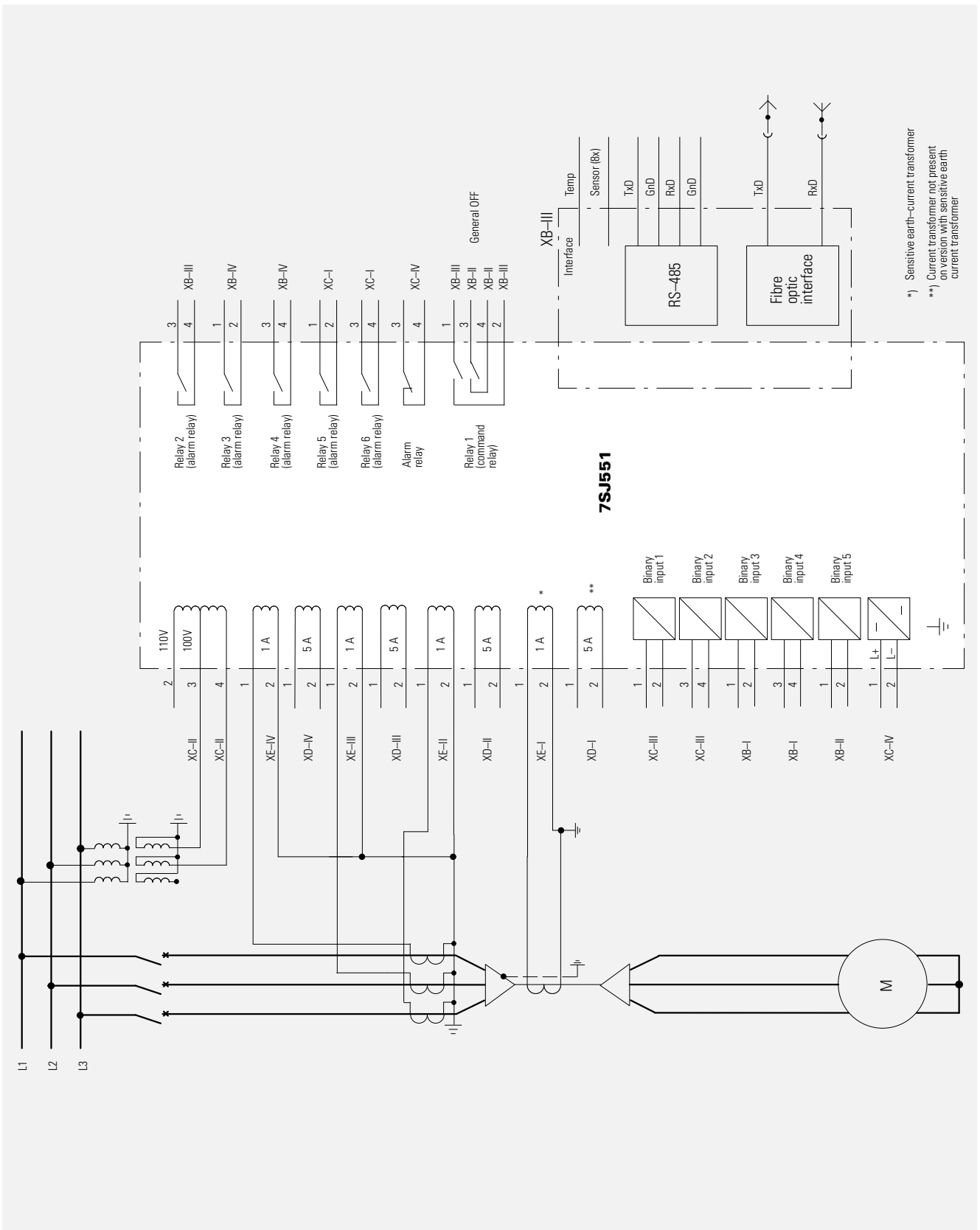


Fig. 3 Application motor protection



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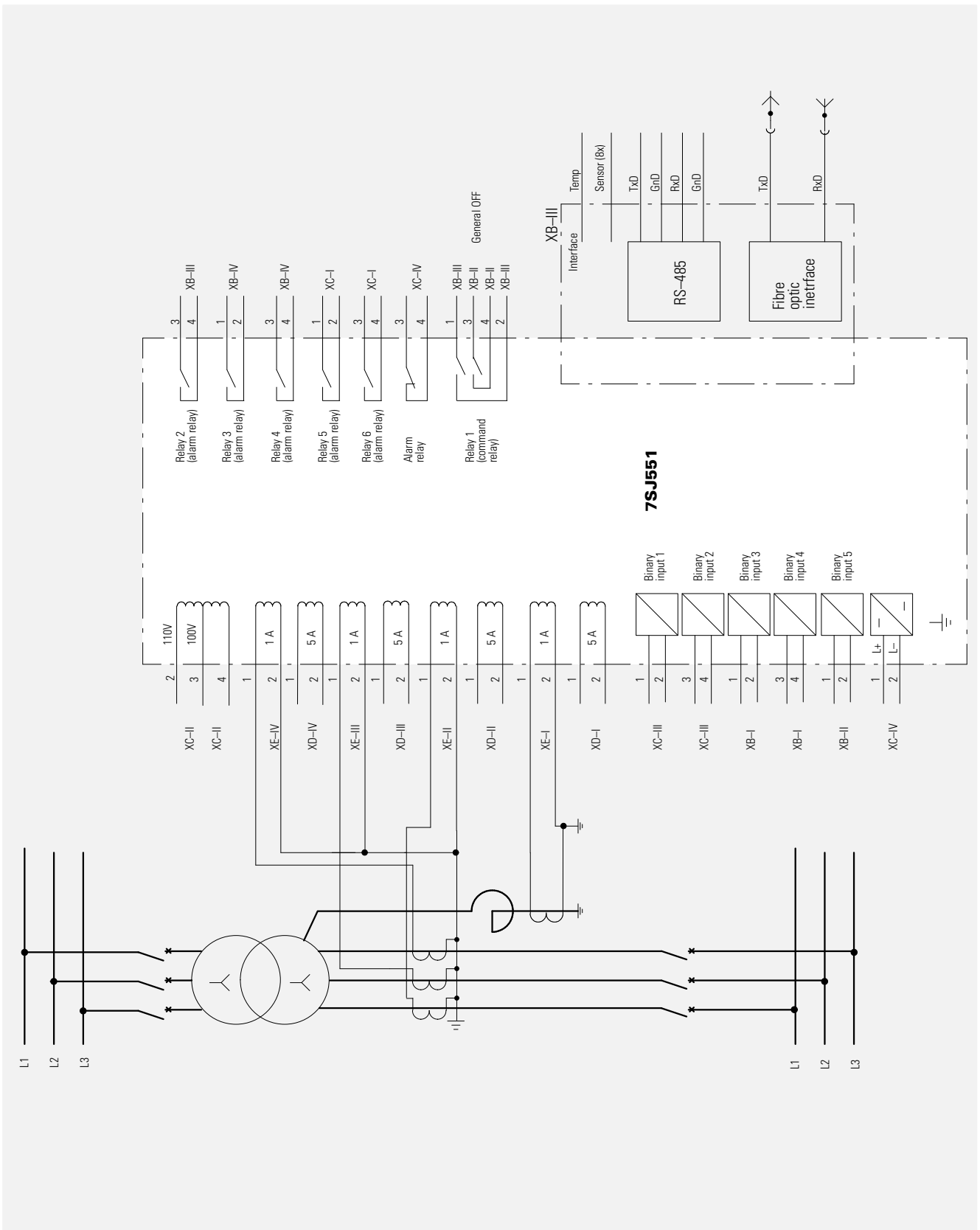


Fig. 4  
Application transformer protection

# Motor Protection

**Dimension drawings** in mm

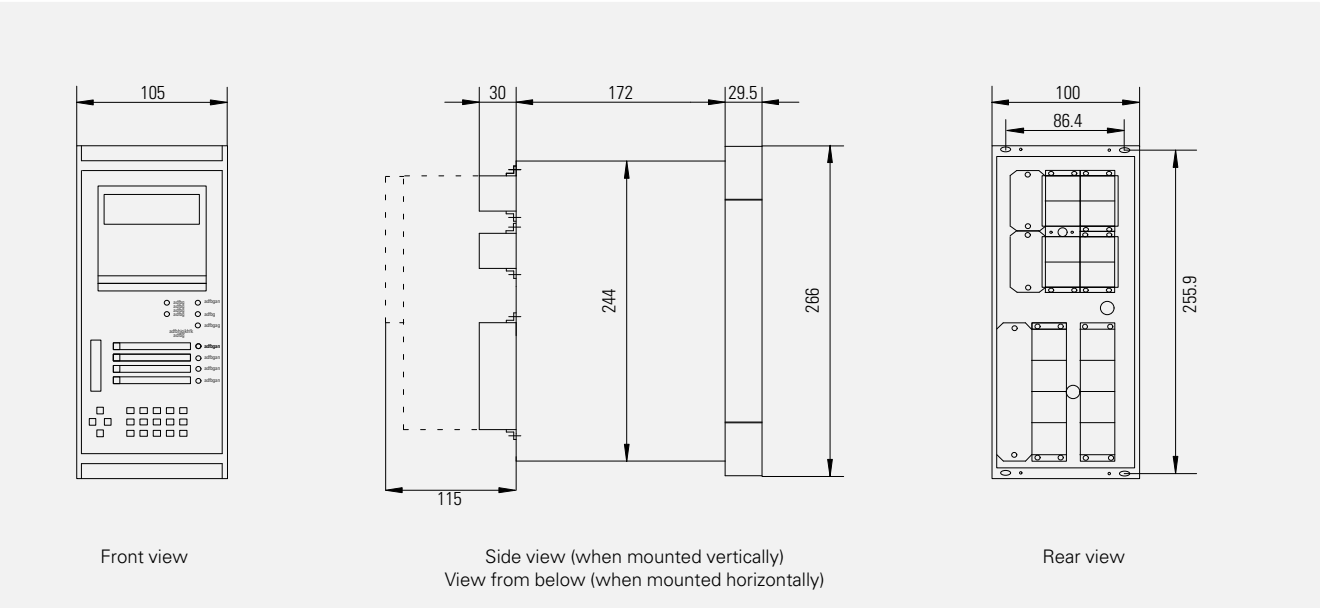


Fig. 5  
7SJ551 in 7XP20 housing

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Siemens Aktiengesellschaft



Power  
Transmission  
and Distribution

Order No.: **E50001-5742-A121-A2-7600**  
Printed in the Federal Republic of Germany  
KG K 0995 5.0 SC 12 En 361 386